# SEMILINEAR STOCHASTIC INTEGRAL EQUATIONS IN $L_{p}$ 

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Abstract: We consider a semilinear parabolic stochastic integral equation

$$
\begin{aligned}
u(t, \omega, x)= & A k_{\alpha} * u(t, \omega, x)+\sum_{k=1}^{\infty} k_{\beta} \star G^{k}(t, \omega, u(t, \omega, \cdot))(x) \\
& +k_{\gamma} * F(t, \omega, u(t, \omega, \cdot))(x)+u_{0}(\omega, x)+t u_{1}(\omega, x)
\end{aligned}
$$

Here $t \in[0, T], \omega$ in a probability space $\Omega, x$ in a $\sigma$-finite measure space $B$ with (positive) measure $\Lambda$. The kernels $k_{\mu}(t)$ are multiples of $t^{\mu-1}$. The operator $A: \mathcal{D} A \subset L_{p}(B) \rightarrow L_{p}(B)$ is such that $(-A)$ is a nonnegative operator. The convolution integrals $k_{\beta} \star G^{k}$ are stochastic convolutions with respect to independent scalar Wiener processes $w^{k} . F:[0, T] \times \Omega \times \mathcal{D}(-A)^{\theta} \rightarrow L_{p}(B)$ and $G:[0, T] \times \Omega \times \mathcal{D}(-A)^{\theta} \rightarrow L_{p}\left(B, l_{2}\right)$ are nonlinear with suitable Lipschitz conditions.

We establish an $L_{p}$-theory for this equation, including existence and uniqueness of solutions, and regularity results in terms of fractional powers of $(-A)$ and fractional derivatives in time.

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WOLFGANG DESCH AND STIG-OLOF LONDEN

AbStract. We consider a semilinear parabolic stochastic integral equation

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Dedicated to Herbert Amann on the occasion of his 70th birthday.

## 1. Introduction

We consider the semilinear integral equation

$$
\begin{align*}
u(t, \omega, x)= & A \int_{0}^{t} k_{\alpha}(t-s) u(s, \omega, x) d s \\
& +\sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) G^{k}(s, \omega, u(s, \omega, \cdot))(x) d w_{s}^{k}  \tag{1.1}\\
& +\int_{0}^{t} k_{\gamma}(t-s) F(s, \omega, u(s, \omega, \cdot))(x) d s+u_{0}(\omega, x)+t u_{1}(\omega, x)
\end{align*}
$$

The real scalar valued solution $u(t, \omega, x)$ depends on $t \in[0, T], \omega$ in a probability space $\Omega$, and $x$ in a measure space $B$. The convolution kernels $k_{\mu}$ are defined by

$$
\begin{equation*}
k_{\mu}(t):=\frac{1}{\Gamma(\mu)} t^{\mu-1} \tag{1.2}
\end{equation*}
$$

We assume $\alpha \in(0,2), \beta>\frac{1}{2}$, and $\gamma>0$. The operator $A: \mathcal{D} A \subset L_{p}(B ; \mathbb{R}) \rightarrow$ $L_{p}(B ; \mathbb{R})$ (with $\left.2 \leq p<\infty\right)$ is such that $(-A)$ is a nonnegative linear operator (see Section 2 below). In particular we have in mind elliptic partial differential operators on a sufficiently smooth (bounded or unbounded) domain $B \subset \mathbb{R}^{n}$, but formally we require only that $(-A)$ is sectorial and the state space is an $L_{p}$-space on some measure space $B$. The processes $w_{s}^{k}$ are scalar valued, independent Wiener processes. $F$ and $G^{k}$ are nonlinear and satisfy suitable Lipschitz estimates with respect to $u$. The functions $u_{0}$ and $u_{1}$ are given initial data. For the precise conditions, see Section 3.

[^0]Our goal is to establish existence and uniqueness of solutions for the semilinear equation (1.1) in an $L_{p}$-framework with $p \in[2, \infty)$. Regularity results will be stated in terms of fractional powers of $-A$ (for spatial regularity) and fractional time integrals and derivatives as well as Hölder continuity (for time regularity).

Technically we rely primarily on results concerning a linear integral equation where the forcing terms $F$ and $G$ are replaced by functions independent of $u$, i.e., (5.1). In recent work [12] we have developed an $L_{p}$-theory for (5.1), albeit without the deterministic part and without the $u_{1}$-term. These results need, however, - for the purpose of analyzing (1.1) - to be extended and to be made more precise.

Our linear results build on an approach due to Krylov, developed for parabolic stochastic partial differential equations. This approach uses the Burkholder-Davis-Gundy inequality and estimates on the solution and on its spatial gradient. To analyze the integral equation (5.1) we combine Krylov's approach with transformation techniques and estimates involving both fractional powers of $-A$, and fractional time-derivatives (integrals) of the solution. Krylov's approach is very efficient in obtaining maximal regularity, however, it relies on a highly nontrivial Paley-Littlewood inequality [18]. A counterpart of this estimate can be given for general sectorial $A$ by straightforward estimates on the Dunford integral, when we allow for an infinitesimal loss of regularity.

We also include results for the deterministic convolution and for the $u_{1}$-term. Obviously, no originality is claimed for these results.

To obtain result on the semilinear equation (1.1) we combine our linear theory with a standard contraction approach.

The paper is organized as follows: Before we can state our main results, we need to collect some facts about sectorial operators and fractional differentiation and integration in Section 2. Section 3 states the hypotheses and results for the semilinear equation. In Section 4 we provide the tools to define a stochastic integral and a stochastic convolution in $L_{p}$-spaces. The central part of this section is an application of the Burkholder-Davis-Gundy inequality to lift scalar valued Ito-integrals to stochastic integrals in $L_{p}$. This approach is adapted from [19]. Section 5 deals with the linear fractional differential equation. In the beginning we give the results on existence and regularity which are basic to obtain similar results on the semilinear equation. We construct the solution via the resolvent operator and a variation of parameters formula. The contribution of the initial data and of the forcing $F$, which enters as a Lebesgue integral, are well-known ([24], [33]). The contribution of the stochastic integral containing $G$ is handled by a recent result [12]. We collect these results in a unified way to allow a comparison of the various requirements on regularity. In Section 6 we arrive at the proof of our main results on the semilinear equation by a standard contraction procedure. In Section 7 we make some comments on available maximal regularity results for the linear equation and their implications for the semilinear equation. Finally, in Section 8 we compare our results to some recent results on parabolic stochastic differential equations obtained recently using an abstract theory of stochastic integration in Banach spaces.

## 2. Fractional powers and fractional derivatives

In this paper $A: \mathcal{D} A \subset L_{p}(B ; \mathbb{R}) \rightarrow L_{p}(B ; \mathbb{R})$ will be a linear operator such that $(-A)$ is nonnegative. Here $p \in[2, \infty)$, but fixed. Regularity in space will be expressed in terms of the fractional powers $(-A)^{\theta}$ of $A$. Regularity in time will be expressed in terms of fractional time derivatives $D_{t}^{\eta} f$. In corollaries we will also give regularity results in terms of the function spaces $h_{0 \rightarrow 0}^{\gamma}([0, T] ; X)$, i.e., the little Hölder-continuous functions with $f(0)=0$.

In this section we summarize briefly the definitions and some known results about nonnegative operators, their fractional powers, and about fractional integration and differentiation.

Let $X$ be a complex Banach space and let $\mathcal{L}(X)$ be the space of bounded linear operators on $X$. Let $B$ be a closed, linear map of $\mathcal{D} B \subset X$ into $X$. The operator $-B$ is said to be nonnegative if $\rho(B)$, the resolvent set of $B$, contains $(0, \infty)$, and

$$
\sup _{\lambda>0}\left\|\lambda(\lambda I-B)^{-1}\right\|_{\mathcal{L}(X)}<\infty
$$

An operator is positive if it is nonnegative and, in addition, $0 \in \rho(B)$. For $\omega \in[0, \pi)$, we define

$$
\Sigma_{\omega}:=\{\lambda \in \mathbb{C} \backslash\{0\}| | \arg \lambda \mid<\omega\} .
$$

Recall that if $(-B)$ is nonnegative, then there exists a number $\eta \in(0, \pi)$ such that $\rho(B) \supset \Sigma_{\eta}$, and

$$
\begin{equation*}
\sup _{\lambda \in \Sigma_{\eta}}\left\|\lambda(\lambda I-B)^{-1}\right\|_{\mathcal{L}(X)}<\infty \tag{2.1}
\end{equation*}
$$

The spectral angle of $(-B)$ is defined by

$$
\phi_{(-B)}:=\inf \left\{\omega \in(0, \pi] \mid \rho(B) \supset \Sigma_{\pi-\omega}, \sup _{\lambda \in \Sigma_{\pi-\omega}}\left\|\lambda(\lambda I-B)^{-1}\right\|_{\mathcal{L}(X)}<\infty\right\}
$$

We will rely on the concept of fractional powers of $(-B)$ : Let $(-B)$ be a densely defined nonnegative linear operator on $X$, and $\theta>0$. If $(-B)$ is positive, then $(-B)^{-1}$ is a bounded operator, and $(-B)^{-\theta}$ can be defined by integral formulas [4, Ch. 3] or [20, Section 2.2.2]. As usual,

$$
\begin{equation*}
(-B)^{\theta}:=\left((-B)^{-\theta}\right)^{-1}, \quad \theta>0 \tag{2.2}
\end{equation*}
$$

If $(-B)$ is nonnegative with $0 \in \sigma(-B)$, we proceed as in [4, Ch. 5]: Since $(-B+\epsilon I)$ is a positive operator if $\epsilon>0$, its fractional power $(-B+\epsilon I)^{\theta}$ is well defined according to (2.2). We define

$$
\begin{align*}
\mathcal{D}\left((-B)^{\theta}\right) & :=\left\{y \in \bigcap_{0<\epsilon \leq \epsilon_{0}} \mathcal{D}\left((-B+\epsilon I)^{\theta}\right) \mid \lim _{\epsilon \rightarrow 0+}(-B+\epsilon I)^{\theta} y \text { exists }\right\}  \tag{2.3}\\
(-B)^{\theta} y & :=\lim _{\epsilon \rightarrow 0+}(-B+\epsilon I)^{\theta} y \quad \text { for } y \in \mathcal{D}\left((-B)^{\theta}\right) \tag{2.4}
\end{align*}
$$

Lemma 2.1. Let $-B$ be a nonnegative linear operator on a Banach space $X$ with spectral angle $\phi_{(-B)}$, and let $\theta>0$.

1) $(-B)^{\theta}$ is closed and $\overline{\mathcal{D}\left((-B)^{\theta}\right)}=\overline{\mathcal{D}(-B)}$.
2) Assume that $\theta \phi_{(-B)}<\pi$. Then $(-B)^{\theta}$ is nonnegative and has spectral angle $\theta \phi_{(-B)}$.
Proof. For (1) see [4, p. 109, 142], also [7, Theorem 10]. For (2) see [4, p. 123].
Lemma 2.2. Let $-B$ be a nonnegative linear operator on a Banach space $X$ with spectral angle $\phi_{(-B)}$. Then for $\eta \in\left[0, \pi-\phi_{(-B)}\right)$

$$
\begin{equation*}
\sup _{|\arg \mu| \leq \eta, \mu \neq 0}\left\|(-B)^{\theta} \mu^{1-\theta}(\mu I-B)^{-1}\right\|_{\mathcal{L}(X)}<\infty \tag{2.5}
\end{equation*}
$$

Proof. In case $\eta=0$, see [4, Th. 6.1.1, p. 141]. The general case can be reduced to the case $\mu>0,[14$, p.314]. See also [12, Lemma 3.3].

We turn now to fractional differentiation and integration in time:
Definition 2.3. Let $X$ be a Banach space and $\alpha \in(0,1)$, let $u \in L_{1}((0, T) ; X)$ for some $T>0$.

1) Fractional integration in time of order $\alpha$ is defined by $D_{t}^{-\alpha} u:=\frac{1}{\Gamma(\alpha)} t^{\alpha-1} * u$.
2) We say that $u$ has a fractional derivative of order $\alpha>0$ provided $u=D_{t}^{-\alpha} f$, for some $f \in L_{1}((0, T) ; X)$. If this is the case, we write $D_{t}^{\alpha} u=f$.
Remark 2.4. Suppose that $u$ has a fractional derivative of order $\alpha \in(0,1)$. Then $\frac{1}{\Gamma(1-\alpha)} t^{-\alpha} * u$ is differentiable a.e. and absolutely continuous with $D_{t}^{\alpha} u=$ $\frac{d}{d t}\left(\frac{1}{\Gamma(1-\alpha)} t^{-\alpha} * u\right)$.

For the equivalence of fractional derivatives in $L_{p}$ and fractional powers of the realization of the derivative in $L_{p}$, we have the following Lemma.

Lemma 2.5. [8, Prop.2] Let $p \in[1, \infty), X$ a Banach space and define

$$
\mathcal{D} L:=\left\{u \in W^{1, p}((0, T) ; X) \mid u(0)=0\right\}, L u=u^{\prime} \text { for } u \in \mathcal{D} L
$$

Then, with $\beta \in(0,1)$,

$$
\begin{equation*}
L^{\beta} u=D_{t}^{\beta} u, \quad u \in \mathcal{D}\left(L^{\beta}\right) \tag{2.6}
\end{equation*}
$$

where $\mathcal{D}\left(L^{\beta}\right)$ coincides with the set of functions $u$ having a fractional derivative in $L_{p}$, i.e.,

$$
\mathcal{D}\left(L^{\beta}\right)=\left\{u \in L_{p}((0, T) ; X) \left\lvert\, \frac{1}{\Gamma(1-\beta)} t^{-\beta} * u \in W_{0}^{1, p}((0, T) ; X)\right.\right\}
$$

In particular, $D_{t}^{\beta}$ is closed.
We refer to [8] for further properties of the operator $D_{t}^{\beta}$.

## 3. The main Result

Hypothesis 3.1. Let $(B, \mathcal{A}, \Lambda)$ be a $\sigma$-finite measure space and fix $2 \leq p<\infty$. Let $(-A): \mathcal{D} A \subset L_{p}(B ; \mathbb{R}) \rightarrow L_{p}(B ; \mathbb{R})$ be a nonnegative linear operator with spectral angle $\phi_{(-A)}$, and such that $\mathcal{D} A \cap L_{1}(B ; \mathbb{R}) \cap L_{\infty}(B ; \mathbb{R})$ is dense in $L_{p}(B ; \mathbb{R})$.

Hypothesis 3.2. Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space with an increasing, right continuous filtration $\left\{\mathcal{F}_{t} \mid t \geq 0\right\}$ satisfying $\mathcal{F}_{t} \subset \mathcal{F}$ for all $t \geq 0$. Let $\mathcal{P}$ denote the predictable $\sigma$-algebra on $[0, \infty) \times \Omega$ generated by $\left\{\mathcal{F}_{t}\right\}$, and assume that $\left\{w_{s}^{k} \mid k=\right.$ $1,2,3, \ldots\}$ is an independent family of (scalar valued) $\mathcal{F}_{t}$-adapted Wiener processes on $(\Omega, \mathcal{F}, \mathbb{P})$.

Remark 3.3. On $[0, T] \times \Omega$, measurability will always be understood with respect to the predictable $\sigma$-algebra $\mathcal{P}$, and the product measure of the Lebesgue measure on $[0, T]$ and $\mathbb{P}$.

Hypothesis 3.4. For suitable $\theta \in[0,1)$ and $\epsilon \in[0,1)$, the function

$$
F:[0, T] \times \Omega \times \mathcal{D}(-A)^{\theta} \rightarrow \mathcal{D}(-A)^{\epsilon}
$$

satisfies the following assumptions:
(a) For fixed $u \in \mathcal{D}(-A)^{\theta}$, the function $F(\cdot, \cdot, u)$ is measurable from $[0, T] \times \Omega$ into $\mathcal{D}(-A)^{\epsilon}$.
(b) There exists a constant $M_{F}>0$, such that for all $t \in[0, T]$, and all $u_{1}, u_{2} \in$ $\mathcal{D}(-A)^{\theta}$ the following Lipschitz estimate holds

$$
\begin{equation*}
\left\|F\left(t, \omega, u_{1}\right)-F\left(t, \omega, u_{2}\right)\right\|_{\mathcal{D}(-A)^{\epsilon}} \leq M_{F}\left\|u_{1}-u_{2}\right\|_{\mathcal{D}(-A)^{\theta}} \quad \text { for a.e. } \omega \in \Omega \text {. } \tag{3.1}
\end{equation*}
$$

(c) For $u=0$ we have

$$
\begin{equation*}
\left[\int_{\Omega} \int_{0}^{T}\|F(t, \omega, 0)\|_{\mathcal{D}(-A)^{\epsilon}}^{p} d t d \mathbb{P}\right]^{1 / p}=M_{F, 0}<\infty \tag{3.2}
\end{equation*}
$$

Hypothesis 3.5. For the same $\theta \in[0,1)$ as in Hypothesis 3.4, the function

$$
\begin{aligned}
& G:[0, T] \times \Omega \times \mathcal{D}(-A)^{\theta} \rightarrow L_{p}\left(B ; l_{2}\right) \\
& {[G(t, \omega, u)](x):=\left(G^{k}(t, \omega, u)(x)\right)_{k=1}^{\infty}}
\end{aligned}
$$

satisfies the following assumptions:
(a) For fixed $u \in \mathcal{D}(-A)^{\theta}$, the function $G(\cdot, \cdot, u)$ is measurable from $[0, T] \times \Omega$ into $L_{p}\left(B ; l_{2}\right)$.
(b) There exists a constant $M_{G}>0$, such that for all $t \in[0, T]$, and all $u_{1}, u_{2} \in$ $\mathcal{D}(-A)^{\theta}$ the following Lipschitz estimate holds:

$$
\begin{equation*}
\left\|G\left(t, \omega, u_{1}\right)-G\left(t, \omega, u_{2}\right)\right\|_{L_{p}\left(B ; l_{2}\right)} \leq M_{G}\left\|u_{1}-u_{2}\right\|_{\mathcal{D}(-A)^{\theta}} \quad \text { for a.e. } \omega \in \Omega \text {. } \tag{3.3}
\end{equation*}
$$

(c) For $u=0$ we have

$$
\begin{equation*}
\left[\int_{\Omega} \int_{0}^{T}\|G(t, \omega, 0)\|_{L_{p}\left(B ; l_{2}\right)}^{p} d t d \mathbb{P}\right]^{1 / p}=M_{G, 0}<\infty \tag{3.4}
\end{equation*}
$$

Theorem 3.6. Let the probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and the Wiener processes $\left(w_{s}^{k}\right)_{k=1}^{\infty}$ be as in Hypothesis 3.2. Let $p \in[2, \infty)$, let the measure space $(B, \mathcal{A}, \Lambda)$ and the operator $A: \mathcal{D} A \subset L_{p}(B ; \mathbb{R}) \rightarrow L_{p}(B ; \mathbb{R})$ satisfy Hypothesis 3.1. Let $\alpha \in(0,2)$, $\beta>\frac{1}{2}$ and $\gamma>0$. Let $T>0$ and assume that $F:[0, T] \times \Omega \times \mathcal{D}(-A)^{\theta} \rightarrow \mathcal{D}(-A)^{\epsilon}$ and $G:[0, T] \times \Omega \times \mathcal{D}(-A)^{\theta} \rightarrow L_{p}\left(B ; l_{2}\right)$ satisfy Hypotheses 3.4 and 3.5 with suitable $\theta, \epsilon \in[0,1]$. Let $u_{0} \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{0}}\right)$, $u_{1} \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)$, with suitable $\delta_{i} \in[0,1]$, both $u_{i}$ measurable with respect to $\mathcal{F}_{0}$. Suppose that the following inequalities hold:

$$
\begin{align*}
& \alpha \theta<\gamma+\alpha \epsilon,  \tag{3.5}\\
& \frac{1}{2}+\alpha \theta<\beta  \tag{3.6}\\
& \alpha \theta<\frac{1}{p}+\alpha \delta_{0},  \tag{3.7}\\
& \alpha \theta<1+\frac{1}{p}+\alpha \delta_{1} . \tag{3.8}
\end{align*}
$$

Then there exists a unique function $u \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$ such that for almost all $t \in[0, T]$

$$
\int_{0}^{t} k_{\alpha}(t-s) u(s, \omega, \cdot) d s \in \mathcal{D} A \quad \text { for a.e. } \omega \in \Omega
$$

and (1.1) is satisfied for almost all $t \in[0, T]$ and almost all $\omega \in \Omega$.
Theorem 3.7. Let the assumptions of Theorem 3.6 hold. Moreover, assume that $\eta \in(-1,1), \zeta \in[0,1]$ are such that

$$
\begin{align*}
& \eta+\alpha \zeta<\gamma+\alpha \epsilon  \tag{3.9}\\
& \frac{1}{2}+\eta+\alpha \zeta<\beta  \tag{3.10}\\
& \eta+\alpha \zeta<\frac{1}{p}+\alpha \delta_{0}  \tag{3.11}\\
& \eta+\alpha \zeta<1+\frac{1}{p}+\alpha \delta_{1} \tag{3.12}
\end{align*}
$$

With the notation $1_{\{a>b\}}=1$ if $a>b$ and $1_{\{a>b\}}=0$ if $a \leq b$, we put

$$
\begin{equation*}
v(t)=u(t)-1_{\left\{\delta_{0}>\zeta\right\}} u_{0}-1_{\left\{\delta_{1}>\zeta\right\}} t u_{1}-1_{\{\epsilon>\zeta\}} \int_{0}^{t} k_{\gamma}(t-s) F(s, \omega, u(s)) d s \tag{3.13}
\end{equation*}
$$

(a) Then, if $\eta>0$, the function $v$, considered as a Banach space valued function $v:[0, T] \rightarrow L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)$, has a fractional derivative of order $\eta$.
(b) If $\eta<0$, the function $v:[0, T] \rightarrow L_{p}\left(\Omega ; L_{p}(B ; \mathbb{R})\right)$ has a fractional integral of order $-\eta$. Moreover, $D_{t}^{\eta} v$ takes values in $L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)$.
(c) If $\eta=0$, of course, we denote $D_{t}^{0} v=v$.

In any case, there exists a constant $M_{u}$, depending on $A, p, T, \alpha, \beta, \gamma, \delta_{i}, \epsilon, \zeta, \eta$, $\theta, M_{F}, M_{G}$ such that

$$
\begin{align*}
& \left\|D_{t}^{\eta} v\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\varsigma}\right)}  \tag{3.14}\\
\leq & M_{u}\left[\left\|u_{0}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{0}}\right)}+\left\|u_{1}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)}+M_{F, 0}+M_{G, 0}\right] .
\end{align*}
$$

Corollary 3.8. Let the Assumptions of Theorem 3.6 hold. Let $\zeta \in[0,1]$. Let $u$ be the solution of (1.1) and $v$ be defined by (3.13).
(1) Let $p<q<\infty$ be such that

$$
\begin{aligned}
& \frac{1}{p}-\frac{1}{q}+\alpha \zeta<\gamma+\alpha \epsilon, \quad \frac{1}{2}+\frac{1}{p}-\frac{1}{q}+\alpha \zeta<\beta \\
& \alpha \zeta-\frac{1}{q}<\alpha \delta_{0}, \quad \alpha \zeta-\frac{1}{q}<1+\alpha \delta_{1} .
\end{aligned}
$$

Then $v \in L_{q}\left([0, T] ; L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)\right)$.
(2) Let $\mu \in\left(0,1-\frac{1}{p}\right)$ be such that

$$
\begin{aligned}
& \frac{1}{p}+\mu+\alpha \zeta<\gamma+\alpha \epsilon, \quad \frac{1}{2}+\frac{1}{p}+\mu+\alpha \zeta<\beta \\
& \mu+\alpha \zeta<\alpha \delta_{0}, \quad \mu+\alpha \zeta<1+\alpha \delta_{1}
\end{aligned}
$$

Then $v \in h_{0 \rightarrow 0}^{\mu}\left([0, T] ; L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)\right)$.
Hypothesis 3.9. Let $F_{1}, F_{2}:[0, T] \times \Omega \times \mathcal{D}(-A)^{\theta} \rightarrow \mathcal{D}(-A)^{\epsilon}$ satisfy Hypothesis 3.4, $G_{1}, G_{2}:[0, T] \times \Omega \times \mathcal{D}(-A)^{\theta} \rightarrow L_{p}\left(B ; l_{2}\right)$ satisfy Hypothesis 3.5 , and suppose that there are nonnegative functions $\mu_{\Delta F}, \mu_{\Delta G} \in L_{p}([0, T] \times \Omega ; \mathbb{R})$ such that for all $t \in[0, T]$ and $u \in \mathcal{D}(-A)^{\theta}$, and almost all $\omega \in \Omega$

$$
\begin{align*}
\left\|F_{1}(t, \omega, u)-F_{2}(t, \omega, u)\right\|_{\mathcal{D}(-A)^{\epsilon}} & \leq \mu_{\Delta F}(t, \omega)  \tag{3.15}\\
\left\|G_{1}(t, \omega, u)-G_{2}(t, \omega, u)\right\|_{L_{p}\left(B ; l_{2}\right)} & \leq \mu_{\Delta G}(t, \omega) \tag{3.16}
\end{align*}
$$

Remark 3.10. The standard example of $F_{i}, G_{i}$ satisfying Hypothesis 3.9 is (for $i=1,2$ ):

$$
\begin{aligned}
F_{i}(t, \omega, u) & =F(t, \omega, u)+f_{i}(t, \omega), \\
G_{i}(t, \omega, u) & =G(t, \omega, u)+g_{i}(t, \omega)
\end{aligned}
$$

where $F$ and $G$ satisfy Hypotheses 3.4 and 3.5 , respectively, and $f_{i} \in L_{p}([0, T] \times$ $\left.\Omega ; \mathcal{D}(-A)^{\epsilon}\right), g_{i} \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$. Here we take

$$
\begin{aligned}
\mu_{\Delta F}(t, \omega) & =\left\|f_{1}(t, \omega)-f_{2}(t, \omega)\right\|_{\mathcal{D}(-A)^{\epsilon}} \\
\mu_{\Delta G}(t, \omega) & =\left\|g_{1}(t, \omega)-g_{2}(t, \omega)\right\|_{L_{p}\left(B ; l_{2}\right)}
\end{aligned}
$$

Theorem 3.11. Let the probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and the Wiener processes $w_{s}^{k}$ be as in Hypothesis 3.2. Let $p \in[2, \infty)$, let the measure space $(B, \mathcal{A}, \Lambda)$ and the operator $A: \mathcal{D} A \subset L_{p}(B ; \mathbb{R}) \rightarrow L_{p}(B ; \mathbb{R})$ satisfy Hypothesis 3.1.

Let $T>0, \alpha \in(0,2), \beta>\frac{1}{2}, \gamma>0$, and $\delta_{0}, \delta_{1}, \epsilon \in[0,1]$ be such that (3.5), (3.6), (3.7), and (3.8) hold. Let $\eta \in(-1,1)$ and $\zeta \in[0,1]$ be such that (3.9), (3.10), (3.11), (3.12) hold. Then there exists a constant $M_{\Delta u}>0$, dependent on $p, T, \alpha, \beta, \gamma, \delta_{0}, \delta_{1}, \epsilon, \zeta, M_{F}, M_{G}$, such that the following Lipschitz estimate holds:

Let $F_{1}, F_{2}, G_{1}, G_{2}$ satisfy Hypotheses 3.4, 3.5 and 3.9 with $\epsilon, \theta$ as above. For $i=1,2$ let the initial data $u_{0, i} \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{0}}\right)$ and $u_{1, i} \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)$ be $\mathcal{F}_{0}$ measurable, and let $u_{1}(t, \omega, x), u_{2}(t, \omega, x)$ be the solutions of (1.1) with $F, G, u_{0}, u_{1}$ replaced by $F_{i}, G_{i}, u_{0, i}, u_{1, i}$. Let $v_{i}$ be defined according to (3.13) with $u$ replaced by $u_{i}$. Then

$$
\begin{align*}
& \left\|D_{t}^{\eta} v_{1}-D_{t}^{\eta} v_{2}\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\varsigma}\right)}  \tag{3.17}\\
& \leq \quad M_{\Delta u}\left[\left\|u_{0,1}-u_{0,2}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\left.\delta_{0}\right)}\right.}+\left\|u_{1,1}-u_{1,2}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)}\right. \\
& \left.\quad+\left\|\mu_{\Delta F}(t, \omega)+\mu_{\Delta G}(t, \omega)\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})}\right] .
\end{align*}
$$

## 4. Stochastic lemmas

Lemma 4.1 ([19],Theorem 3.10). Let $(\Omega, \mathcal{F}, \mathbb{P})$ satisfy Hypothesis 3.2. Let $Y$ be a dense subspace of $L_{p}(B ; \mathbb{R}), 0<T \leq \infty$, and $g \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$. Then there exists a sequence of functions $g_{j} \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$ converging to $g$ in $L_{p}\left([0, T] \times \Omega, L_{p}\left(B ; l_{2}\right)\right)$ such that each $g_{j}=\left(g_{j}^{k}\right)_{k=1}^{\infty}$ is of the form

$$
g_{j}^{k}(t, \omega, x)= \begin{cases}\sum_{i=1}^{j} I_{\tau_{i-1}^{j}(\omega)<t \leq \tau_{i}^{j}(\omega)}(t) g_{j, i}^{k}(x) & \text { if } k \leq j  \tag{4.1}\\ 0 & \text { else }\end{cases}
$$

where $\tau_{0}^{j} \leq \tau_{1}^{j} \leq \cdots \tau_{j}^{j}$ are bounded stopping times with respect to the filtration $\mathcal{F}_{t}$, and $g_{j, i}^{k} \in Y$. (Here, for any set $A, I_{A}$ denotes its indicator function.)

Remark 4.2. We will apply Lemma 4.1 with $Y=\mathcal{D} A \cap L_{1}(B ; \mathbb{R}) \cap L_{\infty}(B ; \mathbb{R})$.
Lemma 4.3. Let $(\Omega, \mathcal{F}, \mathbb{P})$ and the Wiener processes $w_{t}^{k}$ be as in Hypothesis 3.2. Let $p \in[2, \infty)$. Let $Y$ be a dense subspace of $L_{p}(B ; \mathbb{R})$, let $T>0$, and let $g_{j} \in$ $L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$ be of the simple structure given in (4.1). For $t \in[0, T]$, let $V(t): Y \rightarrow L_{p}(B ; \mathbb{R})$ be a linear operator such that the function $t \mapsto V(t) y$ is in $L_{2}\left([0, T] ; L_{p}(B ; \mathbb{R})\right)$ for each $y \in Y$. Then there exists a constant $M$, depending only on $p$ and $T$, such that for all $t \in(0, T]$

$$
\begin{align*}
& \int_{B} \int_{\Omega}\left|\sum_{k=1}^{j} \int_{0}^{t}\left[V(t-s) g_{j}^{k}(s, \omega)\right](x) d w_{s}^{k}\right|^{p} d \mathbb{P}(\omega) d \Lambda(x)  \tag{4.2}\\
\leq & M \int_{B} \int_{\Omega}\left(\int_{0}^{t}\left|\left[V(t-s) g_{j}(s, \omega)\right](x)\right|_{l_{2}}^{2} d s\right)^{\frac{p}{2}} d \mathbb{P}(\omega) d \Lambda(x) .
\end{align*}
$$

Proof. First fix some $t \in(0, T]$. For $x \in B, r>0$ we define

$$
Y_{j}(r, \omega, x)=\sum_{k=1}^{j} \int_{0}^{r}\left[V(t-s) g_{j}^{k}(s, \omega)\right](x) d w_{s}^{k}
$$

By the elementary structure of $g_{j}$,

$$
\int_{0}^{r}\left|\left[V(t-s) g_{j}^{k}(s, \omega)\right](x)\right|^{2} d s<\infty
$$

for allmost all $x \in B$, so that $Y_{j}(r, \omega, x)$ is well-defined as an Ito integral for such $x$, and it is a martingale. Since the Wiener processes $w_{s}^{k}$ are independent, the quadratic variation of $Y_{j}(\cdot, \cdot, x)$ is

$$
\sum_{k=1}^{j} \int_{0}^{r}\left|\left[V(t-s) g_{j}^{k}(s, \omega)\right](x)\right|^{2} d s
$$

Now the Burkholder-Davis-Gundy inequality (see [17, p. 163]) yields for $r \in[0, t]$ and each $x \in B$,

$$
\begin{align*}
& \int_{\Omega}\left|\sum_{k=1}^{j} \int_{0}^{r}\left[V(t-s) g_{j}^{k}(s, \omega)\right](x) d w_{s}^{k}\right|^{p} d \mathbb{P}(\omega)  \tag{4.3}\\
\leq & M \int_{\Omega}\left(\int_{0}^{r} \sum_{k=1}^{j}\left|\left[V(t-s) g_{j}^{k}(s, \omega)\right](x)\right|^{2} d s\right)^{\frac{p}{2}} d \mathbb{P}(\omega) \\
= & \left.\left.M \int_{\Omega}\left(\int_{0}^{r} \mid V(t-s) g_{j}(s, \omega)\right](x)\right|_{l_{2}} ^{2} d s\right)^{\frac{p}{2}} d \mathbb{P}(\omega) .
\end{align*}
$$

In (4.3), take $r=t$ and integrate over $B$ :

$$
\begin{aligned}
& \int_{B} \int_{\Omega}\left|\sum_{k=1}^{j} \int_{0}^{t}\left[V(t-s) g_{j}^{k}(s, \omega)\right](x) d w_{s}^{k}\right|^{p} d \mathbb{P}(\omega) d \Lambda(x) \\
\leq & M \int_{B} \int_{\Omega}\left(\int_{0}^{t}\left|\left[V(t-s) g_{j}(s, \omega)\right](x)\right|_{l_{2}}^{2} d s\right)^{\frac{p}{2}} d \mathbb{P}(\omega) d \Lambda(x) .
\end{aligned}
$$

Lemma 4.4. Let $(\Omega, \mathcal{F}, \mathbb{P})$ and the Wiener processes $w_{t}^{k}$ satisfy Hypothesis 3.2. Let $T>0,2 \leq p<\infty$, and $g \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$, moreover, let $\left\{g_{j}\right\}$ be a sequence approximating $g$ in the sense of Lemma 4.1. Let $\beta>\frac{1}{2}, \eta \in[0,1)$ such that $\beta-\eta>\frac{1}{2}$. Then the functions

$$
D_{t}^{\eta} \sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) g_{j}^{k}(s, \omega, x) d w_{s}^{k}(\omega)
$$

converge in $L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)$, as $j \rightarrow \infty$.
Proof. Put $h_{i, j}^{k}:=g_{j}^{k}-g_{i}^{k}$. The stochastic Fubini theorem implies that

$$
\begin{aligned}
& \quad D_{t}^{-\eta} \int_{0}^{t} k_{\beta-\eta}(t-s) h_{i, j}^{k}(s, \omega, x) d w_{s}^{k}=\int_{0}^{t} k_{\beta}(t-s) h_{i, j}^{k}(s, \omega, x) d w_{s}^{k} \\
& \text { i.e., } \quad \int_{0}^{t} k_{\beta-\eta}(t-s) h_{i, j}^{k}(s, \omega, x) d w_{s}^{k}=D_{t}^{\eta} \int_{0}^{t} k_{\beta}(t-s) h_{i, j}^{k}(s, \omega, x) d w_{s}^{k}
\end{aligned}
$$

We use Lemma 4.3 and the fact that $k_{\beta-\eta}^{2} \in L_{1}([0, T] ; \mathbb{R})$ :

$$
\begin{aligned}
& \int_{0}^{T} \int_{B} \int_{\Omega}\left|D_{t}^{\eta} \sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) h_{i, j}^{k}(s, \omega, x) d w_{s}^{k}\right|^{p} d \mathbb{P}(\omega) d \Lambda(x) d t \\
= & \int_{0}^{T} \int_{B} \int_{\Omega}\left|\sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta-\eta}(t-s) h_{i, j}^{k}(s, \omega, x) d w_{s}^{k}\right|^{p} d \mathbb{P}(\omega) d \Lambda(x) d t \\
\leq & M \int_{0}^{T} \int_{B} \int_{\Omega}\left(\int_{0}^{t}\left|k_{\beta-\eta}(t-s) h_{i, j}(s, \omega, x)\right|_{l_{2}}^{2} d s\right)^{\frac{p}{2}} d \mathbb{P}(\omega) d \Lambda(x) d t \\
\leq & M \int_{B} \int_{\Omega}\left[\int_{0}^{T} k_{\beta-\eta}^{2}(s) d s\right]^{\frac{p}{2}}\left[\int_{0}^{T}\left|h_{i, j}(s, \omega, x)\right|_{l_{2}}^{p} d s\right] d \mathbb{P}(\omega) d \Lambda(x) \\
\leq & M\left\|h_{i, j}\right\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)}^{p} .
\end{aligned}
$$

As $i, j \rightarrow \infty$, we have $h_{i, j} \rightarrow 0$ in $L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$, thus $D_{t}^{\eta} \sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-$ $s) g_{j}^{k}(s, \omega, x) d w_{s}^{k}(\omega)$ is a Cauchy sequence in $L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)$.

Definition 4.5. Let $(\Omega, \mathcal{F}, \mathbb{P})$ and the Wiener processes $w_{t}^{k}$ satisfy Hypothesis 3.2. Let $T>0,2 \leq p<\infty$, and $g \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$, moreover, let $\left\{g_{j}\right\}$ be a sequence approximating $g$ in the sense of Lemma 4.1. Let $\beta>\frac{1}{2}$. Then we define

$$
\begin{aligned}
\left(k_{\beta} \star g\right)(t, \omega) & :=\sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) g^{k}(s, \omega, x) d w_{s}^{k}(\omega) \\
& :=\lim _{j \rightarrow \infty} \sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) g_{j}^{k}(s, \omega, x) d w_{s}^{k}(\omega) .
\end{aligned}
$$

## 5. Linear theory

In this section we replace the semilinear inhomogeneity in (1.1) by inhomogeneities independent of $u$, so that we obtain a linear integral equation:

$$
\begin{align*}
u(t, \omega, x)= & A \int_{0}^{t} k_{\alpha}(t-s) u(s, \omega, x) d s  \tag{5.1}\\
& +\sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) g^{k}(s, \omega, x) d w_{s}^{k} \\
& +\int_{0}^{t} k_{\gamma}(t-s) f(s, \omega, x) d s+u_{0}(\omega, x)+t u_{1}(\omega, x)
\end{align*}
$$

We will prove the following propositions by a chain of Lemmas:
Proposition 5.1. Let the probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and the Wiener processes $\left(w_{s}^{k}\right)_{k=1}^{\infty}$ be as in Hypothesis 3.2. Let $p \in[2, \infty)$, let the measure space $(B, \mathcal{A}, \Lambda)$ and the operator $A: \mathcal{D} A \subset L_{p}(B ; \mathbb{R}) \rightarrow L_{p}(B ; \mathbb{R})$ satisfy Hypothesis 3.1. Assume that $T>0$ and let $f \in L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)$, and $g \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B, l_{2}\right)\right)$. Let $u_{0} \in L_{p}\left(\Omega ; L_{p}(B ; \mathbb{R})\right)$ and $u_{1} \in L_{p}\left(\Omega ; L_{p}(B ; \mathbb{R})\right)$ be $\mathcal{F}_{0}$-measurable.

Let $\alpha \in(0,2), \beta>\frac{1}{2}, \gamma>0$. Then there exists a unique function $u \in L_{p}([0, T] \times$ $\left.\Omega ; L_{p}(B, \mathbb{R})\right)$ such that for almost all $t \in[0, T]$

$$
\int_{0}^{t} k_{\alpha}(t-s) u(s, \omega, \cdot) d s \in \mathcal{D} A \quad \text { for a.e. } \omega \in \Omega
$$

and (5.1) holds for almost all $\omega \in \Omega$ and almost all $t \in[0, T]$.
Proposition 5.2. Let the assumptions of Proposition 5.1 hold. Suppose that $f \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right), u_{0} \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{0}}\right)$ and $u_{1} \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)$ with suitable $\epsilon, \delta_{0}, \delta_{1} \in[0,1)$. Let $u$ be as in Proposition 5.1. Let $\eta \in(-1,1), \zeta \in[0,1]$ satisfy

$$
\begin{align*}
& \eta+\alpha \zeta<\gamma+\alpha \epsilon  \tag{5.2}\\
& \frac{1}{2}+\eta+\alpha \zeta<\beta  \tag{5.3}\\
& \eta+\alpha \zeta<\frac{1}{p}+\alpha \delta_{0}  \tag{5.4}\\
& \eta+\alpha \zeta<1+\frac{1}{p}+\alpha \delta_{1} \tag{5.5}
\end{align*}
$$

With the notation $1_{\{a>b\}}=1$ if $a>b$ and $1_{\{a>b\}}=0$ else, we put

$$
v(t)=u(t)-1_{\left\{\delta_{0}>\zeta\right\}} u_{0}-1_{\left\{\delta_{1}>\zeta\right\}} t u_{1}-1_{\{\epsilon>\zeta\}} \int_{0}^{t} k_{\gamma}(t-s) f(s) d s
$$

(a) Then, if $\eta>0$, the function $v$, considered as a Banach space valued function $v:[0, T] \rightarrow L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)$, has a fractional derivative of order $\eta$.
(b) If $\eta<0$, the function $v:[0, T] \rightarrow L_{p}\left(\Omega ; L_{p}(B ; \mathbb{R})\right)$ has a fractional integral of order $-\eta$. Moreover, $D_{t}^{\eta} v$ takes values in $L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)$.
(c) If $\eta=0$, clearly $D_{t}^{0} v=v$.

In either case, there exist constants $M_{\mathrm{init}}, M_{T, \mathrm{Leb}}$, and $M_{T, \mathrm{Ito}}$ depending on $p, T$, $\alpha, \beta, \gamma, \delta_{0}, \delta_{1}, \epsilon, \zeta, \eta$ such that

$$
\begin{align*}
& \quad\left\|D_{t}^{\eta} v(t)\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\varsigma}\right)}  \tag{5.6}\\
& \leq \quad M_{\text {init }}\left[\left\|u_{0}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{0}}\right)}+\left\|u_{1}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\left.\delta_{1}\right)}\right.}\right] \\
& \quad+M_{T, \text { Leb }}\|f\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right)}+M_{T, \text { Ito }}\|g\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B, l_{2}\right)\right)} .
\end{align*}
$$

Moreover, the constants $M_{T, \text { Leb }}$ and $M_{T, \text { Ito }}$ can be made arbitrarily small by chosing the time interval $[0, T]$ sufficiently short.

The proof of the propositions above relies on the concept of a resolvent operator (see [24]), introduced by the following definition:

Definition 5.3. Let $A$ satisfy Hypothesis 3.1 , let $\alpha \in(0,2)$ and $\beta>0$. For $t>0$ we define the resolvent operator $S_{\alpha, \beta}(t): L_{p}(B ; \mathbb{R}) \rightarrow L_{p}(B ; \mathbb{R})$ by

$$
\begin{equation*}
S_{\alpha, \beta}(t) x:=\frac{1}{2 \pi i} \int_{\Gamma_{\rho, \phi}} e^{\lambda t} \lambda^{\alpha-\beta}\left(\lambda^{\alpha}-A\right)^{-1} x d \lambda \tag{5.7}
\end{equation*}
$$

along the contour

$$
\Gamma_{\rho, \phi}(t)= \begin{cases}(t-\phi+\rho) e^{i \phi} & \text { for } t>\phi \\ \rho e^{i t} & \text { for } t \in(-\phi, \phi) \\ (-t-\phi+\rho) e^{-i \phi} & \text { for } t<-\phi\end{cases}
$$

with $\rho>0, \phi>\frac{\pi}{2}, \alpha \phi+\phi_{A}<\pi$.
For $\beta=1$, this definition coincides with the known notion of a resolvent operator, c.f. [24]. For $\beta>1, S_{\alpha, \beta}$ could be obtained by fractional integration of $S_{\alpha, 1}$.

Equation (5.1) is formally solved by the variation of parameters formula

$$
\begin{align*}
u(t)= & S_{\alpha, 1}(t) u_{0}+S_{\alpha, 2}(t) u_{1}  \tag{5.8}\\
& +\int_{0}^{t} S_{\alpha, \gamma}(t-s) f(s) d s+\int_{0}^{t} \sum_{k=1}^{\infty} S_{\alpha, \beta}(t-s) g(s) d w_{s}^{k}
\end{align*}
$$

The task of the proof is to make sense of this formal expression in suitable function spaces, and to show that it gives a solution of (5.1). Moreover, the estimates claimed in Proposition 5.2 need to be verified. Since the equation is linear, all terms $u_{0}, u_{1}, f, g$ can be treated separately. This is done in the following Lemmas 5.6, 5.7, and 5.9. Uniqueness can be proved by the standard reduction to a deterministic homogeneous equation with zero initial data, which has only the zero solution by the well-known theory of deterministic evolutionary integral equations (see [24]).

First we collect some basic facts about the resolvent operator:
Lemma 5.4. Let $A$ satisfy Hypothesis 3.1, let $\alpha \in(0,2)$ and $\beta>0$. The resolvent operator defined above has the following properties:

1) For all $t>0$ and all $\zeta \in[0,1]$, the operator $S_{\alpha, \beta}(t)$ is a bounded linear operator $L_{p}(B, \mathbb{R}) \rightarrow \mathcal{D}(-A)^{\zeta}$.
2) For all $x \in L_{p}(B ; \mathbb{R})$, the function $t \mapsto S_{\alpha, \beta}(t) x$ can be extended analytically to some sector in the right half plane.
3) For all $x \in L_{p}(B ; \mathbb{R})$ and all $t>0$, we have

$$
\begin{align*}
& \int_{0}^{t} k_{\alpha}(t-s)\left\|S_{\alpha, \beta}(s) x\right\|_{L_{p}(B ; \mathbb{R})} d s<\infty \\
& \int_{0}^{t} k_{\alpha}(t-s) S_{\alpha, \beta}(s) x d s \in \mathcal{D} A \\
& S_{\alpha, \beta}(t) x=A \int_{0}^{t} k_{\alpha}(t-s) S_{\alpha, \beta}(s) x d s+k_{\beta}(t) x \tag{5.9}
\end{align*}
$$

4) Let $T>0, \delta, \zeta \in[0,1]$, and $\eta \in(-1,1)$ such that

$$
\begin{equation*}
\eta+\alpha \zeta<\beta+\alpha \delta \tag{5.10}
\end{equation*}
$$

Let $x \in \mathcal{D}(-A)^{\delta}$ and put

$$
v(t)= \begin{cases}S_{\alpha, \beta}(t) x & \text { if } \delta \leq \zeta \\ S_{\alpha, \beta}(t) x-k_{\beta}(t) x & \text { if } \delta>\zeta\end{cases}
$$

(a) Then, if $\eta>0$, the function $v$, considered as a Banach-space valued function $v:[0, T] \rightarrow \mathcal{D}(-A)^{\zeta}$, admits a fractional derivative of order $\eta$.
(b) If $\eta<0$, the function $v:[0, T] \mapsto L_{p}(B ; \mathbb{R})$, has a fractional integral of order $-\eta$. Moreover, $D_{t}^{\eta} v$ takes values in $\mathcal{D}(-A)^{\zeta}$.
(c) If $\eta=0$, we write $D_{t}^{0} v=v$.

In either case, there exists some $M>0$ (dependent on $A, \alpha, \beta, \zeta, \delta, \eta$ ) such that for all $t \in(0, T]$ and all $x \in \mathcal{D}(-A)^{\delta}$,

$$
\begin{equation*}
\left\|D_{t}^{\eta} v(t)\right\|_{\mathcal{D}(-A)^{\varsigma}} \leq M t^{(\beta+\alpha \delta)-(\eta+\alpha \zeta)-1}\|x\|_{\mathcal{D}(-A)^{\delta}} \tag{5.11}
\end{equation*}
$$

Remark 5.5. In fact, if $x \in \mathcal{D}(-A)^{\delta}$ with $\delta \geq \zeta$ and $\beta>\eta$, the function $t \mapsto k_{\beta}(t) x$ admits a fractional derivative $D_{t}^{\eta} k_{\beta} x=k_{\beta-\eta} x$ in $\mathcal{D}(-A)^{\zeta}$. In this case, (5.10) holds, and both functions, $S_{\alpha, \beta}(t) x$ and $S_{\alpha, \beta}(t) x-k_{\beta}(t) x$ admit fractional derivatives of order $\eta$ in $\mathcal{D}(-A)^{\zeta}$. On the other hand, evidently, if $\beta \leq \eta$ or $x \notin \mathcal{D}(-A)^{\zeta}$, at most one of the two functions above can have a fractional derivative of order $\eta$ in $\mathcal{D}(-A)^{\zeta}$.

Proof. All these results come out of standard estimates of the contour integral, along with the usual analyticity arguments. Since the estimate (5.11) is crucial in the sequel, we give a more detailed proof.

First we consider the case $\delta \leq \zeta$ where we can utilize Lemma 2.2 with $\theta=0$ for $\rho$ in a suitable sector:

$$
\left\|(\rho-A)^{-1} x\right\|_{\mathcal{D}(-A)^{\varsigma}} \leq M|\rho|^{\zeta-\delta-1}\|x\|_{\mathcal{D}(-A)^{\delta}} .
$$

Formally, the Laplace transform of $D_{t}^{\eta} S_{\alpha, \beta} x$ is $\lambda^{\eta+\alpha-\beta}\left(\lambda^{\alpha}-A\right)^{-1} x$. We show that the contour integral

$$
w(t):=\frac{1}{2 \pi i} \int_{\Gamma_{\rho, \phi}} e^{\lambda t} \lambda^{\eta+\alpha-\beta}\left(\lambda^{\alpha}-A\right)^{-1} x d \lambda
$$

exists in $\mathcal{D}(-A)^{\zeta}$, if (5.10) holds.

$$
\begin{aligned}
& \left\|\int_{\Gamma_{\rho, \phi}} e^{\lambda t} \lambda^{\eta+\alpha-\beta}\left(\lambda^{\alpha}-A\right)^{-1} x d \lambda\right\|_{\mathcal{D}(-A)^{\varsigma}} \\
= & \left\|\int_{\Gamma_{t \rho, \phi}} e^{\mu}\left(\frac{\mu}{t}\right)^{\eta+\alpha-\beta}\left(\left(\frac{\mu}{t}\right)^{\alpha}-A\right)^{-1} x \frac{1}{t} d \mu\right\|_{\mathcal{D}(-A)^{\varsigma}} \\
= & t^{\beta-\alpha-\eta-1}\left\|\int_{\Gamma_{1, \phi}} e^{\mu} \mu^{\eta+\alpha-\beta}\left(\left(\frac{\mu}{t}\right)^{\alpha}-A\right)^{-1} x d \mu\right\|_{\mathcal{D}(-A)^{\varsigma}} \\
\leq & t^{\beta-\alpha-\eta-1} \int_{\Gamma_{1, \phi}} e^{\Re(\mu)}|\mu|^{\alpha+\eta-\beta}\left\|\left(\left(\frac{\mu}{t}\right)^{\alpha}-A\right)^{-1} x\right\|_{\mathcal{D}(-A)^{\varsigma}}|d \mu| \\
\leq & t^{\beta-\alpha-\eta-1} \int_{\Gamma_{1, \phi}} e^{\Re(\mu)}|\mu|^{\alpha+\eta-\beta} M\left|\frac{\mu}{t}\right|^{\alpha(\zeta-\delta-1)}\|x\|_{\mathcal{D}(-A)^{\delta}}|d \mu| \\
= & t^{\beta-\eta-\alpha \zeta+\alpha \delta-1} M\|x\|_{\mathcal{D}(-A)^{\delta}} \int_{\Gamma_{1, \phi}} e^{\Re(\mu)}|\mu|^{\eta-\beta+\alpha(\zeta-\delta)}|d \mu| .
\end{aligned}
$$

Because of (5.10), $w$ is locally integrable and admits a Laplace transform. It requires some standard complex analysis, to show that $\hat{w}(\lambda)=\lambda^{\eta+\alpha-\beta}\left(\lambda^{\alpha}-A\right)^{-1} x$. Now we have to show that in fact $w=D_{t}^{\eta} S_{\alpha, \beta} x$. First consider the case $\eta>0$ : By the convolution theorem for Laplace transforms we have $\left[\widehat{D_{t}^{-\eta} w}\right](\lambda)=\lambda^{\alpha-\beta}\left(\lambda^{\alpha}-\right.$ $A)^{-1} x$, whence $w=D_{t}^{\eta} S_{\alpha, \beta} x$. In case $\eta<0$, the convolution theorem yields $D_{t}^{\eta} S_{\alpha, \beta} x(\lambda)=\lambda^{\eta} \lambda^{\alpha-\beta}\left(\lambda^{\alpha}-A\right)^{-1} x=\hat{w}(\lambda)$.

To handle the case $\delta>\zeta$, we will use Lemma 2.2 with $\theta=1$ :

$$
\left\|A(\rho-A)^{-1} x\right\|_{\mathcal{D}(-A)^{\varsigma}} \leq M \rho^{\zeta-\delta}\|x\|_{\mathcal{D}(-A)^{\delta}}
$$

Notice first that $\hat{k}_{\beta}(\lambda)=\lambda^{-\beta}$, and

$$
k_{\beta}(t)=\frac{1}{2 \pi i} \int_{\Gamma_{\rho, \phi}} e^{\lambda t} \lambda^{-\beta} d \lambda
$$

Therefore,

$$
\begin{aligned}
S_{\alpha, \beta}(t) x-k_{\beta}(t) x & =\frac{1}{2 \pi i} \int_{\Gamma_{\rho, \phi}} e^{\lambda t}\left[\lambda^{\alpha-\beta}\left(\lambda^{\alpha}-A\right)^{-1} x-\lambda^{-\beta} x\right] d \lambda \\
& =\frac{1}{2 \pi i} \int_{\Gamma_{\rho, \phi}} e^{\lambda t} \lambda^{-\beta} A\left(\lambda^{\alpha}-A\right)^{-1} x d \lambda
\end{aligned}
$$

Now we estimate similarly as above

$$
\begin{aligned}
& \left\|\int_{\Gamma_{\rho, \phi}} e^{\lambda t} \lambda^{\eta-\beta} A\left(\lambda^{\alpha}-A\right)^{-1} x d \lambda\right\|_{\mathcal{D}(-A)^{\zeta}} \\
\leq & \int_{\Gamma_{1, \phi}} e^{\Re(\mu)}\left|\frac{\mu}{t}\right|^{\eta-\beta} M\left|\frac{\mu}{t}\right|^{\alpha(\zeta-\delta)}\|x\|_{\mathcal{D}(-A)^{\delta}} \frac{1}{t}|d \mu| \\
= & M\|x\|_{\mathcal{D}(-A)^{\delta}} t^{-\eta+\beta-\alpha \zeta+\alpha \delta-1} \int_{\Gamma_{1, \phi}} e^{\Re(\mu)}|\mu|^{\eta-\beta+\alpha \zeta-\alpha \delta}|d \mu|
\end{aligned}
$$

Thus, for $t>0$, the following integral exists in $\mathcal{D}(-A)^{\zeta}$ :

$$
\begin{aligned}
w_{1}(t) & :=\frac{1}{2 \pi i} \int_{\Gamma_{\rho, \phi}} e^{\lambda t} \lambda^{\eta-\beta} A\left(\lambda^{\alpha}-A\right)^{-1} x d \lambda, \\
\left\|w_{1}(t)\right\|_{\mathcal{D}(-A)^{\varsigma}} & \leq M t^{(\beta+\alpha \delta)-(\eta+\alpha \zeta)-1}
\end{aligned}
$$

In the end one verifies again that in fact $w_{1}(t)=D_{t}^{\eta} v(t)$.

Lemma 5.6 (Contribution of the initial conditions $u_{0}, u_{1}$ ). Let A satisfy Hypothesis 3.1, let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space, $p \in[2, \infty)$. Let $\alpha \in(0,2), 0<T<\infty$, and $u_{0}, u_{1} \in L_{p}\left(\Omega ; L_{p}(B ; \mathbb{R})\right)$. We define $u(t):=S_{\alpha, 1}(t) u_{0}+S_{\alpha, 2}(t) u_{1}$.

1) The function $u$ exists in $L_{\infty}\left([0, T] ; L_{p}(\Omega \times B ; \mathbb{R})\right)$. For all $t>0$ we have

$$
\begin{aligned}
& \int_{0}^{t} k_{\alpha}(t-s) u(s) d s \in \mathcal{D} A \\
& u(t)=A \int_{0}^{t} k_{\alpha}(t-s) u(s) d s+u_{0}+t u_{1}
\end{aligned}
$$

2) Moreover, suppose that $u_{i} \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{i}}\right)$ with some $\delta_{i} \in[0,1]$. Let $\zeta \in[0,1], \eta \in(-1,1)$ be such that

$$
\begin{align*}
& \eta+\alpha \zeta<\frac{1}{p}+\alpha \delta_{0}  \tag{5.12}\\
& \eta+\alpha \zeta<1+\frac{1}{p}+\alpha \delta_{1} \tag{5.13}
\end{align*}
$$

Put

$$
v(t)=u(t)-1_{\zeta<\delta_{0}} u_{0}-1_{\zeta<\delta_{1}} t u_{1} .
$$

Then $v$ has a fractional derivative of order $\eta$ (if $\eta<0$ : a fractional integral of order $-\eta$ ) which is in $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\zeta}\right)$ and satisfies

$$
\begin{aligned}
& \left\|D_{t}^{\eta} v(t, \omega)\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\varsigma}\right)} \\
\leq \quad & M\left[\left\|u_{0}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{0}}\right)}+\left\|u_{1}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)}\right]
\end{aligned}
$$

with a constant $M$ depending on $p, A, T, \alpha, \delta_{0}, \delta_{1}, \zeta, \eta$.
Proof. This is a straightforward application of Lemma 5.4, applied pointwise for $\omega \in \Omega$, for the special cases $\beta=1$ and $\beta=2$.

Lemma 5.7 (Contribution of $f$ ). Let A satisfy Hypothesis 3.1, let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space, $p \in[2, \infty)$. Let $\alpha \in(0,2), \gamma>0,0<T<\infty$, and $f \in$ $L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)$.

1) For almost $t \in[0, T]$, the following integral exists in $L_{p}(B ; \mathbb{R})$, pointwise for almost all $\omega \in \Omega$, as well as in $L_{p}\left(\Omega ; L_{p}(B ; \mathbb{R})\right)$ :

$$
\begin{equation*}
u(t, \omega)=\int_{0}^{t} S_{\alpha, \gamma}(t-s) f(s, \omega) d s \tag{5.14}
\end{equation*}
$$

Moreover, $u \in L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)$, and for almost all $\omega \in \Omega$ and almost all $t \in[0, T]$,

$$
\begin{aligned}
& \int_{0}^{t} k_{\alpha}(t-s) u(s, \omega) d s \in \mathcal{D} A \\
& u(t, \omega)=A \int_{0}^{t} k_{\alpha}(t-s) u(s, \omega) d s+\int_{0}^{t} k_{\gamma}(t-s) f(s, \omega) d s
\end{aligned}
$$

2) Suppose, in addition, that $f \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right)$ with some $\epsilon \in[0,1]$, let $\eta \in(-1,1), \zeta \in[0,1]$ be such that

$$
\begin{equation*}
\eta+\alpha \zeta<\gamma+\alpha \epsilon \tag{5.15}
\end{equation*}
$$

Put

$$
v(t)= \begin{cases}u(t) & \text { if } \zeta \geq \epsilon \\ u(t)-\int_{0}^{t} k_{\gamma}(t-s) f(s) d s & \text { if } \zeta<\epsilon\end{cases}
$$

Then, if $\eta>0$, the function $t \mapsto v(t) \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)$ has a fractional derivative of order $\eta$ in $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\zeta}\right)$. If $\eta<0$, the function $t \mapsto v(t) \in L_{p}\left(\Omega ; L_{p}(B ; \mathbb{R})\right)$ has a fractional integral of order $-\eta$ with values
in $L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)$. If $\eta=0$, we define $D_{t}^{\eta} v=v$. In either case there exists a constant $M_{T, \text { Leb }}$ dependent on $A, T, p, \alpha, \gamma, \epsilon, \zeta, \eta$ such that

$$
\left\|D_{t}^{\eta} v\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\varsigma}\right)} \leq M_{T, \text { Leb }}\|f\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right)}
$$

Moreover, the constant $M_{T, \text { Leb }}$ can be made arbitrarily small by taking the time interval $[0, T]$ sufficiently short.

Proof. The function $t \mapsto \int_{0}^{t}(t-s)^{\gamma-1}\|f(s)\|_{L_{p}(\Omega \times B, \mathbb{R})} d s$ is the convolution of an $L_{1}$-function and an $L_{p}$-function, therefore it is in $L_{p}([0, T], \mathbb{R})$. From (5.11) with $\delta=\zeta=\eta=0$ we obtain $\left\|S_{\alpha, \gamma}(t)\right\|_{L_{p}(B ; \mathbb{R}) \rightarrow L_{p}(B ; \mathbb{R})} \leq M t^{\gamma-1}$. Consequently, the integral

$$
u(t)=\int_{0}^{t} S_{\alpha, \gamma}(t-s) f(s) d s
$$

exists as an integral in $L_{p}(\Omega \times B ; \mathbb{R})$ for almost all $t$, and $u \in L_{p}\left([0, T] \times \Omega, L_{p}(B, \mathbb{R})\right)$. By standard arguments the integral (5.14) exists also in $L_{p}(B ; \mathbb{R})$ for a.e. $\omega \in \Omega$ and a.e. $t \in[0, T]$. Now (5.9) implies (almost everywhere in $\Omega$ and $[0, T]$ )

$$
\begin{aligned}
& u(t)-\int_{0}^{t} k_{\gamma}(t-s) f(s, \omega) d s \\
= & \int_{0}^{t}\left[S_{\alpha, \gamma}(t-s) f(s, \omega)-k_{\gamma}(t-s) f(s, \omega)\right] d s \\
= & \int_{0}^{t} A\left[\int_{0}^{t-s} k_{\alpha}(\sigma) S_{\alpha, \gamma}(t-s-\sigma) f(s, \omega) d \sigma\right] d s .
\end{aligned}
$$

We use the closedness of $A$ and interchange the order of integrals to obtain

$$
u(t)-\int_{0}^{t} k_{\gamma}(t-s) f(s, \omega) d s=A \int_{0}^{t} k_{\alpha}(\sigma) u(t-\sigma, \omega) d \sigma
$$

This proves Part (1) of the Lemma.
To prove Part (2), let $\eta, \zeta, \epsilon$ be such that (5.15) holds. For shorthand put

$$
V(t) x= \begin{cases}D_{t}^{\eta} S_{\alpha, \gamma} x & \text { if } \epsilon \leq \zeta \\ D_{t}^{\eta}\left[S_{\alpha, \gamma}(t) x-k_{\gamma} x\right] & \text { else }\end{cases}
$$

From (5.11) with $\beta$ replaced by $\gamma$, and $\delta$ replaced by $\epsilon$, we have

$$
\|V(t) x\|_{\mathcal{D}(-A)^{\varsigma}} \leq M t^{(\gamma+\alpha \epsilon)-(\eta+\alpha \zeta)-1}\|x\|_{\mathcal{D}(-A)^{\epsilon}}
$$

We obtain by a straightforward convolution argument that

$$
\left\|\int_{0}^{t} V(t-s) f(s) d s\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\varsigma}\right)} d s \leq M_{t, \text { Leb }}\|f\|_{L_{p}\left(\Omega, \mathcal{D}(-A)^{\epsilon}\right)}
$$

with

$$
M_{T, \text { Leb }}=M \int_{0}^{T} t^{(\gamma+\alpha \epsilon)-(\eta+\alpha \zeta)-1} d t
$$

Clearly, $M_{T, \text { Leb }}$ converges to 0 as $T \rightarrow 0$. All we have to show is that in fact

$$
D_{t}^{\eta} v(t)=\int_{0}^{t} V(t-s) f(s) d s
$$

We treat the case $\eta>0, \epsilon>\zeta$, the other cases are done similarly. The definition of $V(t) x$ yields

$$
\int_{0}^{t} k_{\eta}(s) V(t-s) x d x=S_{\alpha, \gamma}(t) x-k_{\gamma}(t) x
$$

Fubini's Theorem implies

$$
\begin{aligned}
& \int_{0}^{t} k_{\eta}(s) \int_{0}^{t-s} V(t-s-\sigma) f(\sigma) d \sigma d s=\int_{0}^{t} \int_{0}^{t-\sigma} k_{\eta}(s) V(t-\sigma-s) f(\sigma) d s d \sigma \\
& =\int_{0}^{t}\left[S_{\alpha, \gamma}(t-\sigma)-k_{\gamma}(t-\sigma)\right] f(\sigma) d \sigma=v(t)
\end{aligned}
$$

Thus $v(t)$, considered as a function with values in $\mathcal{D}(-A)^{\zeta}$, admits a fractional derivative of order $\eta$ which is $V * f$.

The following Lemma is the key to estimate the contribution of the stochastic integral:

Lemma 5.8. Let $A$ satisfy Hypothesis 3.1, $p \in[2, \infty)$. Let $\alpha \in(0,2), \beta>\frac{1}{2}$, $\zeta \in[0,1]$ and $\eta \in(-1,1)$, such that (5.3) holds, i.e. $\frac{1}{2}+\eta+\alpha \zeta<\beta$. Let $T>0$. Then there exists a constant $\tilde{M}_{T, \text { Ito }}>0$ depending on $A, p, T, \alpha, \beta, \eta, \zeta$ such that for all $h \in L_{p}\left([0, T] ; L_{p}\left(B ; l_{2}\right)\right)$,

$$
\begin{aligned}
& \int_{0}^{T} \int_{B}\left(\int_{0}^{t}\left|(-A)^{\zeta} D_{t}^{\eta} S_{\alpha, \beta}(t-s) h(s, x)\right|_{l_{2}}^{2} d s\right)^{\frac{p}{2}} d \Lambda(x) d t \\
\leq & \tilde{M}_{T, \text { Ito }} \int_{0}^{T} \int_{B}|h(s, x)|_{l_{2}}^{p} d \Lambda(x) d s
\end{aligned}
$$

Moreover, the constant $\tilde{M}_{T, \text { Ito }}$ can be made arbitrarily small by taking the time interval $[0, T]$ sufficiently short.
Proof. Write $V(t):=(-A)^{\zeta} D_{t}^{\eta} S_{\alpha, \beta}(t)$ and notice that by (5.11) (with $\delta=0$ ),

$$
\|V(t)\|_{L_{p}\left(B, l_{2}\right) \rightarrow L_{p}\left(B, l_{2}\right)} \leq M t^{\beta-(\eta+\alpha \zeta)-1}
$$

First assume that $p>2$. Notice that $\frac{p}{2}$ and $\frac{p}{p-2}$ are conjugate exponents. Take $f:[0, T] \times B \rightarrow \mathbb{R}^{+}$such that $\int_{0}^{T} \int_{B} f^{\frac{p}{p-2}}(t, x) d \Lambda(x) d t=1$. We estimate

$$
\begin{aligned}
& \int_{0}^{T} \int_{B} f(t, x) \int_{0}^{t}|V(t-s) h(s, x)|_{l_{2}}^{2} d s d \Lambda(x) d t \\
= & \int_{0}^{T} \int_{0}^{t} \int_{B} f(t, x)|V(t-s) h(s, x)|_{l_{2}}^{2} d \Lambda(x) d s d t \\
\leq & \int_{0}^{T} \int_{0}^{t}\left[\int_{B} f(t, x)^{\frac{p}{p-2}} d \Lambda(x)\right]^{\frac{p-2}{p}}\left[\int_{B}|V(t-s) h(s, x)|_{l_{2}}^{p} d \Lambda(x)\right]^{\frac{2}{p}} d s d t \\
\leq & \int_{0}^{T}\|f(t, \cdot)\|_{L_{\frac{p}{p-2}}^{p}(B ; \mathbb{R})} \int_{0}^{t}\|V(t-s)\|_{L_{p}\left(B ; l_{2}\right) \rightarrow L_{p}\left(B ; l_{2}\right)}^{2}\|h(s, \cdot)\|_{L_{p}\left(B ; l_{2}\right)}^{2} d s d t \\
\leq & {\left[\int_{0}^{T}\|f(t, \cdot)\|_{L_{\frac{p}{p-2}}^{\frac{p}{p-2}}(B ; \mathbb{R})} d t\right]^{\frac{p-2}{p}} } \\
& {\left[\int_{0}^{T}\left|\int_{0}^{t}\|V(t-s)\|_{L_{p}\left(B ; l_{2}\right) \rightarrow L_{p}\left(B ; l_{2}\right)}^{2}\|h(s, \cdot)\|_{L_{p}\left(B ; l_{2}\right)}^{2} d s\right|^{\frac{p}{2}} d t\right]^{\frac{2}{p}} . }
\end{aligned}
$$

Thus

$$
\begin{align*}
& {\left[\int_{0}^{T} \int_{B}\left(\int_{0}^{t}|V(t-s) h(s, x)|_{l_{2}}^{2} d s\right)^{\frac{p}{2}} d \Lambda(x) d t\right]^{\frac{2}{p}} }  \tag{5.16}\\
\leq & {\left[\int_{0}^{T}\left|\int_{0}^{t}\|V(t-s)\|_{L_{p}\left(B ; l_{2}\right) \rightarrow L_{p}\left(B ; l_{2}\right)}^{2}\|h(s, \cdot)\|_{L_{p}\left(B ; l_{2}\right)}^{2} d s\right|^{\frac{p}{2}} d t\right]^{\frac{2}{p}} . }
\end{align*}
$$

For $p=2$, the estimate (5.16) is obvious. In either case, we obtain (by estimating the convolution with respect to $s$ )

$$
\begin{aligned}
& {\left[\int_{0}^{T} \int_{B}\left(\int_{0}^{t}|V(t-s) h(s, x)|_{l_{2}}^{2} d s\right)^{\frac{p}{2}} d \Lambda(x) d t\right]^{\frac{2}{p}} } \\
\leq & \left(\int_{0}^{T}\|V(s)\|_{L_{p}\left(B ; l_{2}\right) \rightarrow L_{p}\left(B ; l_{2}\right)}^{2} d s\right)\left(\int_{0}^{T}\|h(s, .)\|_{L_{p}\left(B ; l_{2}\right)}^{p} d s\right)^{\frac{2}{p}} \\
\leq & M^{2} \int_{0}^{T} s^{2(\beta-(\eta+\alpha \zeta)-1)} d s\|h\|_{L_{p}\left([0, T] ; L_{p}\left(B ; l_{2}\right)\right)}^{2}
\end{aligned}
$$

By (5.3) we infer that $s^{2(\beta-(\eta+\alpha \zeta)-1)}$ is integrable on $[0, T]$ so that

$$
\tilde{M}_{T, \text { Ito }}:=\left[M^{2} \int_{0}^{T} s^{2(\beta-(\eta+\alpha \zeta)-1)} d s\right]^{\frac{p}{2}}
$$

is finite and converges to 0 as $T \rightarrow 0+$.
Lemma 5.9 (Contribution of $g$ ). Let A satisfy Hypothesis 3.1, and let the probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and the Wiener processes $w_{t}^{k}$ be as in Hypothesis 3.2. Let $T>0,2 \leq p<\infty, \alpha \in(0,2)$, and $\beta>\frac{1}{2}$. Let $g \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$ and $\left\{g_{j}\right\}$ be a sequence approximating $g$ in the sense of Lemma 4.1, where the values of $g_{j}^{k}$ are in $\mathcal{D} A \cap L_{1}(B ; \mathbb{R}) \cap L_{\infty}(B ; \mathbb{R})$. Let $k_{\beta} \star g$ be given by Definition 4.5. For $j \in \mathbb{N}$ put

$$
u_{j}(t)=\sum_{k=1}^{j} \int_{0}^{t} S_{\alpha, \beta}(t-s) g_{j}^{k}(s) d w_{s}^{k}
$$

1) The limit $u(t)=\lim _{j \rightarrow \infty} u_{j}(t)$ exists in $L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)$. Moreover, for almost all $t \in[0, T]$ and almost all $\omega \in \Omega$,

$$
u(t, \omega)=A \int_{0}^{t} k_{\alpha}(t-s) u(s, \omega) d s+\left(k_{\beta} \star g\right)(t, \omega)
$$

2) Suppose $0 \leq \zeta \leq 1$ and $\eta \in(-1,1)$ are such that

$$
\begin{equation*}
\eta+\alpha \zeta+\frac{1}{2}<\beta \tag{5.17}
\end{equation*}
$$

Then, if $\eta>0$, the function $u:[0, T] \rightarrow L_{p}\left(\Omega, \mathcal{D}(-A)^{\zeta}\right)$ has a fractional derivative of order $\eta$. If $\eta<0$, then $u:[0, T] \rightarrow L_{p}\left(\Omega ; L_{p}(\Omega, \mathbb{R})\right)$ has a fractional integral of order $-\eta$ with values in $L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)$. If $\eta=0$, we denote $D_{t}^{0} u=u$. In either case there exists a constant $M_{T, \text { Ito }}$ dependent on $A, p, \alpha, \beta, \eta, \zeta$ such that

$$
\left\|D_{t}^{\eta} u\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\varsigma}\right)} \leq M_{T, \mathrm{Ito}}\|g\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)} .
$$

Moreover, the constant $M_{T, \mathrm{Ito}}$ can be made arbitrarily small by choosing the time interval $[0, T]$ sufficiently short.

Proof. First, let $h \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$ be of the elementary structure like the $g_{j}$ in Lemma 4.1. Evidently, the following integral exists

$$
\sum_{k=1}^{\infty} \int_{0}^{t} S_{\alpha, \beta}(t-s) h^{k}(s) d w_{s}^{k}=\sum_{k=1}^{\infty} \sum_{i=1}^{\infty} \int_{\tau_{i-1}^{k}}^{\tau_{i}^{k}} S_{\alpha, \beta}(t-s) h_{i}^{k} d w_{s}^{k}
$$

where $\tau_{i}^{k}$ are suitable stopping times, $h_{i}^{k} \in \mathcal{D} A \cap L_{1}(B ; \mathbb{R}) \cap L_{\infty}(B ; \mathbb{R})$, and the both sums are in fact only finite sums. For $\eta \in(-1,1), \zeta \in[0,1]$, satisfying (5.17),
put $V(t) x=(-A)^{\zeta} D_{t}^{\eta} S_{\alpha, \beta}(t) x$. We apply Lemma 4.3 and integrate for $t \in[0, T]$. Subsequently we apply Lemma 5.8:

$$
\begin{align*}
& \int_{0}^{T} \int_{\Omega}\left\|\sum_{k=1}^{\infty} \int_{0}^{t} V(t-s) h^{k}(s) d w_{s}^{k}\right\|_{L_{p}(B ; \mathbb{R})}^{p} d \mathbb{P}(\omega) d t  \tag{5.18}\\
\leq & M \int_{0}^{T} \int_{B} \int_{\Omega}\left(\int_{0}^{t}|[V(t-s) h(s, \omega)](x)|_{l_{2}}^{2} d s\right)^{\frac{p}{2}} d \mathbb{P}(\omega) d \Lambda(x) d t \\
\leq & M \tilde{M}_{T, \mathrm{Ito}}\|h\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)}^{p} .
\end{align*}
$$

In particular, with $\zeta=\eta=0$, and $h=g_{j}-g_{m}$, we have

$$
\left\|u_{j}-u_{m}\right\|_{L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)} \leq M\left\|g_{j}-g_{m}\right\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)}
$$

so that $\left\{u_{j}\right\}$ is a Cauchy sequence in $L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)$ and has a limit $u$. Without loss of generality, taking a subsequence, if necessary, we may assume that $u_{j}$ converges also pointwise for almost all $t \in[0, T]$. Again we use the simple structure of $g_{j}$, in particular that $g_{j}^{k}(t, \omega) \in \mathcal{D} A$. From (5.9) and the Stochastic Fubini Theorem we obtain

$$
\begin{aligned}
& \int_{0}^{t}\left[S_{\alpha, \beta}(t-\sigma) g_{j}^{k}(\sigma, \omega)-k_{\beta}(t-\sigma) g_{j}^{k}(\sigma, \omega)\right] d w_{\sigma}^{k} \\
= & \int_{0}^{t} A\left[\int_{0}^{t-\sigma} k_{\alpha}(s) S_{\alpha, \beta}(t-\sigma-s) g_{j}^{k}(\sigma, \omega) d s\right] d w_{\sigma}^{k} \\
= & A \int_{0}^{t} \int_{0}^{t-\sigma} k_{\alpha}(s) S_{\alpha, \beta}(t-\sigma-s) g_{j}^{k}(\sigma, \omega) d s d w_{\sigma}^{k} \\
= & A \int_{0}^{t} k_{\alpha}(s) \int_{0}^{t-s} S_{\alpha, \beta}(t-\sigma-s) g_{j}^{k}(\sigma, \omega) d w_{\sigma}^{k} d s .
\end{aligned}
$$

Taking the sum over $k=1 \cdots j$ we obtain

$$
u_{j}(t, \omega)-k_{\beta} \star g_{j}(t, \omega)=A \int_{0}^{t} k_{\alpha}(s) u_{j}(t-s, \omega) d s
$$

Taking limits for $j \rightarrow \infty$ (pointwise a.e. in $[0, T]$ ), and using the closedness of $A$ we have for almost all $t \in[0, T]$

$$
u(t, \omega)-k_{\beta} \star g(t, \omega)=A \int_{0}^{t} k_{\alpha}(s) u(t-s, \omega) d s
$$

Thus Part (1) of the Lemma is proved.
To prove Part (2), let $\eta \in(-1,1)$ and $\zeta \in[0,1]$ satisfy (5.17). With $V(t) x=$ $(-A)^{\zeta} D_{t}^{\eta} S_{\alpha, \beta} x$ and $h=g_{j}$, we obtain from (5.18),

$$
\left\|\int_{0}^{t} \sum_{k=1}^{j} V(t-s) g_{j}^{k}(s) d w_{s}^{k}\right\|_{L_{p}\left([0, T] \times \Omega ; L_{p}(B ; \mathbb{R})\right)} \leq M_{T, \operatorname{Ito}}\left\|g_{j}\right\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)},
$$

with a suitable constant $M_{T, \text { Ito }}$ which converges to 0 as $T \rightarrow 0$. We have to show that in fact

$$
\sum_{k=1}^{j} \int_{0}^{t} V(t-s) g_{j}^{k}(s) d w_{s}^{k}=(-A)^{\zeta} D_{t}^{\eta} u_{j}(t)
$$

First let $\eta>0$. By definition we know that

$$
\int_{0}^{t} k_{\eta}(s) V(t-s) x d s=(-A)^{\zeta} S_{\alpha, \beta}(t) x
$$

Taking integrals and using the Stochastic Fubini Theorem, we obtain

$$
\begin{aligned}
(-A)^{\zeta} u_{j}(t) & =\sum_{k=1}^{j} \int_{0}^{t}(-A)^{\zeta} S_{\alpha, \beta}(t-\sigma) g_{j}^{k}(\sigma, \omega) d w_{\sigma}^{k} \\
& =\sum_{k=1}^{j} \int_{0}^{t} \int_{0}^{t-\sigma} k_{\eta}(s) V(t-\sigma-s) g_{j}^{k}(\sigma, \omega) d s d w_{\sigma}^{k} \\
& =\int_{0}^{t} k_{\eta}(s) \sum_{k=1}^{j} \int_{0}^{t-s} V(t-s-\sigma) g_{j}^{k}(\sigma, \omega) d w_{\sigma}^{k} d s
\end{aligned}
$$

Thus $(-A)^{\zeta} u_{j}$ has a fractional derivative of order $\eta$ which is $V \star g_{j}$. Taking the limit for $j \rightarrow \infty$ we infer that $D_{t}^{\eta}(-A)^{\zeta} u=V \star g$. Now let $\eta<0$. Similarly as above, the Stochastic Fubini Theorem yields

$$
\sum_{k=1}^{j} \int_{0}^{t} V(t-\sigma) g_{j}^{k}(\sigma) d w_{\sigma}^{k}=(-A)^{\zeta} \int_{0}^{t} k_{-\eta}(s) u_{j}(t-s) d s
$$

Again we take the limit for $j \rightarrow \infty$ and use the closedness of $A$, to see that the fractional integral $D_{t}^{\eta} u$ takes values in $\mathcal{D}(-A)^{\zeta}$ with $(-A)^{\zeta} D_{t}^{\eta} u=V \star g$.

## 6. The semilinear equation

This section is devoted to the proof of Theorems 3.6, 3.7, 3.11, and Corollary 3.8.
Lemma 6.1. Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space, let $A$ satisfy Hypothesis 3.1, and let $F$ and $G$ satisfy Hypotheses 3.4 and 3.5. We define the operators

$$
\begin{aligned}
& \mathcal{N}_{F}: L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right) \rightarrow L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right), \\
& \mathcal{N}_{G}: L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right) \rightarrow L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)
\end{aligned}
$$

by

$$
\left[\mathcal{N}_{F} v\right](t, \omega):=F(t, \omega, v(t)), \quad\left[\mathcal{N}_{G} v\right](t, \omega):=G(t, \omega, v(t)) .
$$

(1) Then $\mathcal{N}_{F}$ and $\mathcal{N}_{G}$ are well defined and Lipschitz continuous with Lipschitz constants $M_{F}, M_{G}$, respectively.
(2) Let $F_{1}, F_{2}, G_{1}, G_{2}$ satisfy Hypotheses 3.4, 3.5, and 3.9. Let $v \in L_{p}([0, T] \times$ $\left.\Omega ; \mathcal{D}(-A)^{\theta}\right)$. Then

$$
\begin{aligned}
& \left\|\mathcal{N}_{F_{1}} v-\mathcal{N}_{F_{2}} v\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right)} \leq\left\|\mu_{\Delta F}\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})} \\
& \left\|\mathcal{N}_{G_{1}} v-\mathcal{N}_{G_{2}} v\right\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)} \leq\left\|\mu_{\Delta G}\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})} .
\end{aligned}
$$

Here the constants $M_{F}, M_{G}$ and the functions $\mu_{\Delta F}$ and $\mu_{\Delta G}$ are as in Hypotheses 3.4, 3.5, and 3.9.
Proof. These are straightforward estimates.
Lemma 6.2. Let the assumptions of Theorem 3.6 hold, in addition assume that $\delta_{0} \leq \theta, \delta_{1} \leq \theta$. For $v \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$ let $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]} v:[0, T] \times \Omega \rightarrow$ $L_{p}(B ; \mathbb{R})$ be the unique solution $u$ of

$$
\begin{aligned}
u(t, \omega)= & A \int_{0}^{t} k_{\alpha}(t-s) u(s, \omega) d s+u_{0}+t u_{1} \\
& +\sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) G_{k}(s, \omega, v(s)) d w_{s}^{k} \\
& +\int_{0}^{t} k_{\gamma}(t-s) F(s, \omega, v(s)) d s
\end{aligned}
$$

in the sense of Proposition 5.1.
(1) Then $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]}$ is well defined as a nonlinear operator from $L_{p}([0, T] \times$ $\left.\Omega ; \mathcal{D}(-A)^{\theta}\right)$ into $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$. Moreover, $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]}$ is globally Lipschitz continuous with a Lipschitz constant dependent on A, p, T, $\alpha, \beta$, $\gamma, \epsilon, \theta, M_{F}, M_{G}$.
(2) There exists an equivalent norm on $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$, such that the Lipschitz constant of $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]}$ is smaller than 1. This norm depends on $T, p, A, \alpha, \beta, \gamma, \theta, \epsilon, M_{F}, M_{G}$.
(3) There exists a constant $M$, depending on $A, T, p, M_{F}, M_{G}, \alpha, \beta, \epsilon, \theta, \delta_{0}, \delta_{1}$, such that the following Lipschitz estimate holds:
If $F_{1}, F_{2}, G_{1}, G_{2}$ satisfy Hypotheses 3.4, 3.5, and 3.9, if $u_{0,1}, u_{0,2}$ are in $L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{0}}\right)$ and $u_{1,1}, u_{1,2} \in L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)$, measurable with respect to $\mathcal{F}_{0}$, then for any $v \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$ we have

$$
\begin{aligned}
& \left\|\mathcal{T}_{\left[F_{1}, G_{1}, u_{0,1}, u_{1,1}\right]} v-\mathcal{T}_{\left[F_{2}, G_{2}, u_{0,2}, u_{1,2}\right]} v\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)} \\
\leq & M\left[\left\|u_{0,1}-u_{0,2}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\left.\delta_{0}\right)}\right.}+\left\|u_{1,1}-u_{1,2}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\left.\delta_{1}\right)}\right.}\right. \\
& \left.+\left\|\mu_{\Delta F}\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})}+\left\|\mu_{\Delta G}\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})}\right] .
\end{aligned}
$$

(4) $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]}$ has a unique fixed point $u_{\left[F, G, u_{0}, u_{1}\right]} \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$. Moreover, there exists a constant $M$ dependent on $A, p, T, M_{F}, M_{G}, \alpha$, $\beta, \epsilon, \theta, \delta_{0}, \delta_{1}$ such that the following Lipschitz estimate holds:
If $u_{i, j}, F_{i}, G_{i}$ are as in (3), then

$$
\begin{aligned}
& \left\|u_{\left[F_{1}, G_{1}, u_{0,1}, u_{1,1}\right]}-u_{\left[F_{2}, G_{2}, u_{0,2}, u_{1,2}\right]}\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)} \\
\leq & M\left[\left\|u_{0,1}-u_{0,2}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\left.\delta_{0}\right)}\right.}+\left\|u_{1,1}-u_{1,2}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)}\right. \\
& \left.+\left\|\mu_{\Delta F}\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})}+\left\|\mu_{\Delta G}\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})}\right] .
\end{aligned}
$$

Proof. We recall Proposition 5.2 with $\eta=0$ and $\zeta$ replaced by $\theta$. Notice that the conditions (5.2), and (5.3), (5.4), (5.5) are satisfied. Let $u$ solve

$$
u=A k_{\alpha} * u+k_{\gamma} * f+k_{\beta} \star g+u_{0}+t u_{1}
$$

Notice that with the present choice of coefficients the function $v$ in (5.6) is simply $u$. Thus $u \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$ with

$$
\begin{array}{ll}
\|u(t)\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)}  \tag{6.1}\\
\leq & M_{\text {init }}\left[\left\|u_{0}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{0}}\right)}+\left\|u_{1}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\left.\delta_{1}\right)}\right.}\right] \\
& +M_{T, \text { Leb }}\|f\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right)}+M_{T, \text { Ito }}\|g\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B, l_{2}\right)\right)} .
\end{array}
$$

Given $v \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$, we put $f=\mathcal{N}_{F} v$ and $g=\mathcal{N}_{G} v$ as in Lemma 6.1. Then $f \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right)$ and $g \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$. Thus, by (6.1), $u=\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]} v \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$. In particular for $v=0$ we have

$$
\begin{aligned}
& \left\|\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]}(0)\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)} \\
\leq & M_{\text {init }}\left[\left\|u_{0}\right\|_{L_{p}\left(\Omega, \mathcal{D}(-A)^{\left.\delta_{0}\right)}\right.}+\left\|u_{1}\right\|_{L_{p}\left(\Omega\left(\mathcal{D}(-A)^{\delta_{1}}\right)\right.}\right]+M_{T, \mathrm{Leb}} M_{F, 0}+M_{T, \mathrm{Ito}} M_{G, 0}
\end{aligned}
$$

We could immediately get a Lipschitz estimate for $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]}$ by (6.1), but we will get a better (contraction) estimate in an equivalent norm below.

To prove (2), we recall from Proposition 5.2 that $M_{T, \text { Leb }}$ and $M_{T, \text { Ito }}$ can be taken arbitrarily small, if the time intervals are sufficiently short. In particular, there exists $m \in \mathbb{N}$ such that

$$
M_{T / m, \mathrm{Leb}} M_{F}+M_{T / m, \mathrm{Ito}} M_{G}<\frac{1}{4}
$$

With some $\kappa>0$ to be specified below, we define for $v \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$,

$$
\|v\| \|:=\sum_{q=1}^{m} \kappa^{q}\left[\int_{T(q-1) / m}^{T q / m} \int_{\Omega}\|v(t, \omega)\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right]^{1 / p}
$$

For $q=1, \cdots, m$ we put

$$
\begin{aligned}
F_{q}(t, \omega, v) & :=I_{(q-1) T / m \leq t<q T / m}(t) F(t, \omega, v(t)), \\
G_{q}(t, \omega, v) & :=I_{(q-1) T / m \leq t<q T / m}(t) G(t, \omega, v(t)) .
\end{aligned}
$$

If $v, \tilde{v} \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$, then

$$
\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]} v-\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]} \tilde{v}=\sum_{q=1}^{m} w_{q}
$$

where $w_{q}$ solves

$$
w_{q}=A k_{\alpha} * w_{q}+k_{\gamma} *\left[F_{q}(v)-F_{q}(\tilde{v})\right]+k_{\beta} \star\left[G_{q}(v)-G_{q}(\tilde{v})\right] .
$$

Now $w_{q}=0$ on $\left[0, \frac{T(q-1)}{m}\right]$. Lemma 6.1(1) and (6.1) imply

$$
\begin{aligned}
& \left(\int_{T(q-1) / m}^{T q / m} \int_{\Omega}\left\|w_{q}(t, \omega)\right\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right)^{1 / p} \\
\leq & M_{T / m, \operatorname{Leb}} M_{F}\left(\int_{T(q-1) / m}^{T q / m} \int_{\Omega}\|v(t, \omega)-\tilde{v}(t, \omega)\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right)^{1 / p} \\
& +M_{T / m, \operatorname{Ito}} M_{G}\left(\int_{T(q-1) / m}^{T q / m} \int_{\Omega}\|v(t, \omega)-\tilde{v}(t, \omega)\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right)^{1 / p} \\
\leq & \frac{1}{4}\left(\int_{T(q-1) / m}^{T q / m} \int_{\Omega}\|v(t, \omega)-\tilde{v}(t, \omega)\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right)^{1 / p} .
\end{aligned}
$$

On the intervals $\left[\frac{(r-1) T}{m}, \frac{r T}{m}\right]$ with $r>q$ we have the estimate

$$
\begin{aligned}
& \left(\int_{T(r-1) / m}^{T r / m} \int_{\Omega}\left\|w_{q}(t, \omega)\right\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right)^{1 / p} \\
\leq & \left(\int_{0}^{T} \int_{\Omega}\left\|w_{q}(t, \omega)\right\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right)^{1 / p} \\
\leq & M\left(\int_{T(q-1) / m}^{T q / m} \int_{\Omega}\|v(t, \omega)-\tilde{v}(t, \omega)\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right)^{1 / p} .
\end{aligned}
$$

with $M=M_{F} M_{T, \text { Leb }}+M_{G} M_{T, \text { Ito }}$. We choose $\kappa \in(0,1)$ sufficiently small, such that $M \sum_{r=1}^{\infty} \kappa^{r}<\frac{1}{4}$. We have therefore

$$
\begin{aligned}
& \left\|\mid w_{q}\right\| \|=\sum_{r=q}^{m} \kappa^{r}\left[\int_{T(r-1) / m}^{T r / m} \int_{\Omega}\left\|w_{q}(t, \omega)\right\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right]^{1 / p} \\
\leq & {\left[\frac{1}{4}+M \sum_{r=q+1}^{m} \kappa^{r-q}\right] \kappa^{q}\left[\int_{T(q-1) / m}^{T q / m}\|v(t, \omega)-\tilde{v}(t, \omega)\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right]^{1 / p} } \\
\leq & \frac{1}{2} \kappa^{q}\left[\int_{T(q-1) / m}^{T q / m}\|v(t, \omega)-\tilde{v}(t, \omega)\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right]^{1 / p} .
\end{aligned}
$$

Summing for $q=1, \cdots, m$ we obtain

$$
\begin{aligned}
& \left\|\left|\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]} v-\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]} \tilde{v}\| \| \leq \sum_{q=1}^{m}\left\|\left|w_{q}\right|\right\|\right.\right. \\
\leq & \frac{1}{2} \sum_{q=1}^{m} \kappa^{q}\left[\int_{T(q-1) / m}^{T q / m}\|v(t, \omega)-\tilde{v}(t, \omega)\|_{\mathcal{D}(-A)^{\theta}}^{p} d \mathbb{P}(\omega) d t\right]^{1 / p} \\
= & \left.\frac{1}{2} \right\rvert\,\|v-\tilde{v}\|
\end{aligned}
$$

Part (3) is a straightforward application of (6.1) and Lemma 6.1 (2).
Finally, since for all $F, G, u_{0}, u_{1}$ the operator $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]}$ is a strict contraction with Lipschitz constant $\frac{1}{2}<1$ on $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$ (with the norm $\|\|\cdot\|\|$ ), and since $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]} v$ depends Lipschitz on $F, G, u_{0}, u_{1}$ by Part (3), the standard contraction arguments yield Part (4).

We are now ready to finish the proofs of the main results:
Proof of Theorem 3.6. We may assume without loss of generality that $\delta_{0}, \delta_{1} \leq \theta$. (If any $\delta_{i}$ is greater that $\theta$, it may be replaced by $\theta$.) Obviously, the unique solution of (1.1) in $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)$ is exactly the unique fixed point of $\mathcal{T}_{\left[F, G, u_{0}, u_{1}\right]}$ constructed in Lemma 6.2.

Proof of Theorem 3.7. Let $u$ be the solution of (1.1), thus, with $f=\mathcal{N}_{F} u \in$ $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right)$ and $g=\mathcal{N}_{G} u \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B ; l_{2}\right)\right)$ we have that $u$ solves (5.1). Let $v$ be defined by (3.13). Now, $\zeta, \eta, \delta_{0}, \delta_{1}, \epsilon$ satisfy the conditions of Proposition 5.2 , which yields immediately the required additional regularity results.

Proof of Corollary 3.8. To prove Part (1), choose $\eta$ such that

$$
\frac{1}{p}-\frac{1}{q}<\eta<1
$$

and such that the conditions (3.9), (3.10), (3.11), and (3.12) from Theorem 3.7 are satisfied. Then $D_{t}^{\eta} v \in L_{p}\left([0, T] ; L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)\right)$. Notice that $q<\frac{p}{1-p \eta}$, so that we infer from $\left[8\right.$, p. 421] that $v \in L_{q}\left([0, T] ; L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)\right)$.

To prove Part (2), put $\mu+\frac{1}{p}=\eta$. Consequently the conditions (3.9), (3.10), (3.11), and (3.12) from Theorem 3.7 hold. Then $D_{t}^{\eta} v \in L_{p}\left([0, T] ; L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)\right)$. Then by [8, p. 421] we infer that $v \in h_{0 \rightarrow 0}^{\eta-p^{-1}}\left([0, T] ; L_{p}\left(\Omega ; \mathcal{D}(-A)^{\zeta}\right)\right)$.

Proof of Theorem 3.11. For $i=1,2$, let $u_{\left[F_{i}, G_{i}, u_{0, i}, u_{1, i}\right]}$ be the solution of (1.1) with $u_{0}$ replaced by $u_{0, i}$, etc.. Let $v_{\left[F_{i}, G_{i}, u_{0, i}, u_{1, i}\right]}$ be defined by (3.13) with the obvious modifications. From Lemma 6.2, Part (4) we have a Lipschitz estimate

$$
\begin{aligned}
& \left\|u_{\left[F_{1}, G_{1}, u_{0,1}, u_{1,1}\right]}-u_{\left[F_{2}, G_{2}, u_{0,2}, u_{1,2}\right]}\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\theta}\right)} \leq M d \text { with } \\
& d=\left[\left\|u_{0,1}-u_{0,2}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\left.\delta_{0}\right)}\right.}+\left\|u_{1,1}-u_{1,2}\right\|_{L_{p}\left(\Omega ; \mathcal{D}(-A)^{\delta_{1}}\right)}\right. \\
& \left.\quad+\left\|\mu_{\Delta F}\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})}+\left\|\mu_{\Delta G}\right\|_{L_{p}([0, T] \times \Omega ; \mathbb{R})}\right] .
\end{aligned}
$$

Now let $f_{i}=\mathcal{N}_{F} u_{\left[F_{i}, G_{i}, u_{0, i}, u_{1, i}\right]}$ and $g_{i}=\mathcal{N}_{G} u_{\left[F_{i}, G_{i}, u_{0, i}, u_{1, i}\right]}$. By Lemma 6.1(1) we have

$$
\left\|f_{1}-f_{2}\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\epsilon}\right)} \leq M_{F} M d, \quad\left\|g_{1}-g_{2}\right\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(B, l_{2}\right)\right)} \leq M_{G} M d
$$

The difference $v=v_{\left[F_{1}, G_{1}, u_{0,1}, u_{1,1}\right]}-v_{\left[F_{2}, G_{2}, u_{0,2}, u_{1,2}\right]}$ solves (5.1) with $u_{0}$ replaced by $u_{0,1}-u_{0,2}$, etc.. Proposition 5.2 yields now

$$
\left\|v_{\left[F_{1}, G_{1}, u_{0,1}, u_{1,1}\right]}-v_{\left[F_{2}, G_{2}, u_{0,2}, u_{1,2}\right]}\right\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-A)^{\varsigma}\right)} \leq M d
$$

with a suitable constant $M$.

## 7. Maximal REGULARITY CONSIDERATIONS

In this section, we consider the case that $B=\mathbb{R}^{n}$ and $A=\Delta: W^{2, p}\left(\mathbb{R}^{n}\right) \rightarrow$ $L_{p}\left(\mathbb{R}^{n}\right)$, the Laplacian in $L_{p}\left(\mathbb{R}^{n}\right)$. In this case, a maximum regularity result can be proved. To keep the paper at a resonable size we concentrate on the stochastic part and confine ourselves to the equation

$$
\begin{align*}
u(t, \omega, x)= & \Delta \int_{0}^{t} k_{\alpha}(t-s) u(s, \omega, x) d s  \tag{7.1}\\
& +\sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) G^{k}(s, \omega, u(s, \omega, x)) d w_{s}^{k}
\end{align*}
$$

and the linear equation

$$
\begin{equation*}
u(t, \omega, x)=\Delta \int_{0}^{t} k_{\alpha}(t-s) u(s, \omega, x) d s+\sum_{k=1}^{\infty} \int_{0}^{t} k_{\beta}(t-s) g^{k}(s, \omega, x) d w_{s}^{k} \tag{7.2}
\end{equation*}
$$

Notice that various results on maximal regularity with respect to deterministic forcing functions (see, e.g., [33]) and to inintial data (e.g., [8]) are available. These could be combined with the results given here and adapted to the semilinear case.

For (7.2) we obtain
Proposition 7.1 ([12], Theorem 4.14). For a positive integer $n$, let $\Delta: W^{2, p}\left(\mathbb{R}^{n}\right) \rightarrow$ $L_{p}\left(\mathbb{R}^{n}\right)$ be the Laplacian with $1<p<\infty$. Suppose that the probability space $\Omega$ and the Wiener processes $w^{k}$ satisfy Hypothesis 3.2. Let $T>0, \beta>\frac{1}{2}, \alpha \in(0,2)$, and $g \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(\mathbb{R}^{n}, l_{2}\right)\right)$.
(a) Then there exists a unique function $u \in L_{p}\left([0, T] \times \Omega, L_{p}\left(\mathbb{R}^{n}\right)\right)$ such that for almost all $t \in[0, T]$,

$$
\int_{0}^{t} k_{\alpha}(t-s) u(s) d s \in W^{2, p}\left(\mathbb{R}^{n}\right)
$$

and (7.2) holds.
(b) Moreover, if $\zeta \in[0,1]$ is such that

$$
\begin{equation*}
\alpha \zeta+\frac{1}{2} \leq \beta \tag{7.3}
\end{equation*}
$$

then $u \in L_{p}\left([0, T] \times \Omega, \mathcal{D}(-\Delta)^{\zeta}\right)$, and

$$
\begin{equation*}
\|u\|_{L_{p}\left([0, T] \times \Omega, \mathcal{D}(-\Delta)^{\zeta}\right)} \leq M\|g\|_{L_{p}\left([0, T] \times \Omega, l_{2}\right)} \tag{7.4}
\end{equation*}
$$

with a constant $M$ dependent on $n, T, p, \alpha, \beta, \zeta$.
(c) If strict inequality holds in (7.3), then $M$ in (7.4) can be obtained arbitrarily small by taking sufficiently small $T$.

Proof. Of course, if strict inequality holds in (7.3), then the assertions above are just a special case of Proposition 5.2 with $A=\Delta, u_{0}=u_{1}=0$, and $\eta=0$. But for such $A$ and $\eta$, the assertion of Lemma 5.8 holds also if equality holds in (7.3), with the only exception that $\tilde{M}_{T, \text { Ito }}$ cannot be made small by taking small $T$. See [11, Theorem 1.2]. (To prove this, the general estimates from Lemma 5.4 are replaced by a more sophisticated analysis of the resolvent kernel for the Laplacian, using the heat kernel and its self-similarity properties. This has been done for the heat equation by Krylov in [18], and generalized to the case of integral equations in [11].) Once Lemma 5.8 is established, the proof continues exactly as in Section 5. More details can be found in [12].

Since $M$ in (7.4) cannot be controlled simply by taking short time intervals, we need a more sophisticated Lipschitz condition. (For the heat equation, compare [19, Assumption 5.6].)

Hypothesis 7.2. There exists some $\theta \in(0,1)$ such that

$$
\begin{aligned}
& G:[0, T] \times \Omega \times \mathcal{D}(-\Delta)^{\theta} \rightarrow L_{p}\left(\mathbb{R}^{n} ; l_{2}\right) \\
& {[G(t, \omega, u)](x):=\left(G^{k}(t, \omega, u)(x)\right)_{k=1}^{\infty}}
\end{aligned}
$$

satisfies the following assumptions:
(a) For fixed $u \in \mathcal{D}(-\Delta)^{\theta}$, the function $G(\cdot, \cdot, u)$ is measurable from $[0, T] \times \Omega$ into $L_{p}\left(\mathbb{R}^{n} ; l_{2}\right)$.
(b) For each $\epsilon>0$, there exists a constant $M_{G}(\epsilon)>0$, such that for all $t \in[0, T]$, and all $u_{1}, u_{2} \in \mathcal{D}(-\Delta)^{\theta}$ the following Lipschitz estimate holds:

$$
\begin{align*}
& \left\|G\left(t, \omega, u_{1}\right)-G\left(t, \omega, u_{2}\right)\right\|_{L_{p}\left(\mathbb{R}^{n} ; l_{2}\right)}  \tag{7.5}\\
\leq & {\left[\epsilon^{p}\left\|u_{1}-u_{2}\right\|_{\mathcal{D}(-\Delta)^{\theta}}^{p}+M_{G}(\epsilon)^{p}\left\|u_{1}-u_{2}\right\|_{L_{p}\left(\mathbb{R}^{n}\right)}^{p}\right]^{1 / p} \quad \text { for } \omega \in \Omega \text { a.e.. } }
\end{align*}
$$

(c) For $u=0$ we have

$$
\begin{equation*}
\left[\int_{\Omega} \int_{0}^{T}\|G(t, \omega, 0)\|_{L_{p}\left(\mathbb{R}^{n} ; l_{2}\right)}^{p} d t d \mathbb{P}\right]^{1 / p}=M_{G, 0}<\infty \tag{7.6}
\end{equation*}
$$

Theorem 7.3. Let the probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and the Wiener processes $\left(w_{s}^{k}\right)_{k=1}^{\infty}$ be as in Hypothesis 3.2. Let $p \in[2, \infty)$, and $\Delta$ be the Laplacian on $L_{p}\left(\mathbb{R}^{n}\right)$. Let $\alpha \in(0,2), \beta>\frac{1}{2}$, and $T>0$. Assume that $G:[0, T] \times \Omega \times \mathcal{D}(-\Delta)^{\theta} \rightarrow L_{p}\left(\mathbb{R}^{n} ; l_{2}\right)$ satisfies Hypothesis 7.2 with suitable $\theta \in(0,1)$, such that

$$
\begin{equation*}
\alpha \theta+\frac{1}{2}=\beta \tag{7.7}
\end{equation*}
$$

Then there exists a unique function $u \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right)$ such that for almost all $t \in[0, T]$

$$
\int_{0}^{t} k_{\alpha}(t-s) u(s, \omega, \cdot) d s \in \mathcal{D} \Delta \quad \text { for a.e. } \omega \in \Omega
$$

and (7.1) is satisfied for almost all $\omega \in \Omega$.
Proof. We refine the contraction argument from Section 6. As in Lemma 6.1 we define for $v \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right)$

$$
\mathcal{N}_{G}(v): \begin{cases}{[0, T] \times \Omega} & \rightarrow L_{p}\left(\mathbb{R}^{n} ; l_{2}\right) \\ t \times \omega & \mapsto G(t, \omega, v(t, \omega))\end{cases}
$$

For $g \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(\mathbb{R}^{n}, l_{2}\right)\right)$ we define $\mathcal{S} g:=u \in L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right)$, where $u$ is the solution of (7.2) according to Proposition 7.1 with forcing function $g$. As in Section 6 the desired solution $u$ is a fixed point of the operator $\mathcal{T}:=\mathcal{S} \circ \mathcal{N}_{G}$ which maps $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right)$ into itself.

By (7.4) for $\zeta=0$ and for $\zeta=\theta$ we infer

$$
\begin{aligned}
& \|\mathcal{S} g\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(\mathbb{R}^{n}\right)\right)} \leq M_{0}(T)\|g\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(\mathbb{R}^{n} ; l_{2}\right)\right)}, \\
& \|\mathcal{S} g\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right)} \leq M_{\theta}\|g\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(\mathbb{R}^{n} ; l_{2}\right)\right)},
\end{aligned}
$$

with fixed $M_{\theta}$, while $M_{0}(T)$ can be made arbitrarily small by taking $T$ sufficiently small. We fix $\epsilon>0$ such that $M_{\theta} \epsilon<\frac{1}{8}$ and choose the corresponding $M_{G}(\epsilon)$ according to Hypothesis 7.2. On $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right)$ we introduce the following equivalent norm

$$
\begin{aligned}
& \|v\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right), \text { equiv }}^{p} \\
:= & \int_{0}^{T} \int_{\Omega}\left[\epsilon^{p}\|v(t, \omega)\|_{\mathcal{D}(-\Delta)^{\theta}}^{p}+M_{G}^{p}(\epsilon)\|v(t, \omega)\|_{L_{p}\left(\mathbb{R}^{n}\right)}^{p}\right] d \mathbb{P}(\omega) d t .
\end{aligned}
$$

With respect to this norm, the nonlinear operator

$$
\mathcal{N}_{G}: L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right) \rightarrow L_{p}\left([0, T] \times \Omega ; L_{p}\left(\mathbb{R}^{n} ; l_{2}\right)\right)
$$

has Lipschitz constant 1 by Hypothesis 7.2. On the other hand

$$
\|\mathcal{S} g\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right), \text { equiv }} \leq\left(\epsilon^{p} M_{\theta}^{p}+M_{G}(\epsilon)^{p} M_{0}(T)^{p}\right)^{1 / p}\|g\|_{L_{p}\left([0, T] \times \Omega ; L_{p}\left(\mathbb{R}^{n} ; l_{2}\right)\right)}
$$

We infer that $\mathcal{T}$ is Lipschitz on $L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right)$ with respect to the equivalent norm $\|\cdot\|_{L_{p}\left([0, T] \times \Omega ; \mathcal{D}(-\Delta)^{\theta}\right) \text {,equiv }}$, and if $T$ is sufficiently small, so that $\left(\epsilon^{p} M_{\theta}^{p}+\right.$ $\left.M_{G}(\epsilon)^{p} M_{0}(T)^{p}\right)^{1 / p}<\frac{1}{4}$, then the Lipschitz constant of $\mathcal{T}$ is less than $\frac{1}{4}$. We can now proceed as in Lemma 6.2 (2) to construct an equivalent norm on $L_{p}([0, T] \times$ $\left.\Omega ; \mathcal{D}(-A)^{\theta}\right)$ which makes $\mathcal{T}$ a strict contraction also for large $T$.

## 8. Krylov's Approach Versus B-space Valued Stochastic Integration

At the center of the study of stochastic integral equations in Banach spaces is the problem of defining and estimating stochastic integrals, in particular stochastic convolutions, in Banach spaces. Krylov's approach, which is used in this paper, is elementary in the sense that stochastic integrals are taken pointwise, so they are classical Ito-integrals of scalar valued processes. The Burkholder-Davis-Gundy inequality provides the step from $L_{2}$-estimates to $L_{p}$. Of course, this can only be done for sufficiently "nice" integrands. The final step is to extend the results obtained for smooth initial data and elementary forcing terms to more general $L_{p}$-data by a completion argument.

On the other hand, the recent progress on stochastic integration in Banach spaces (see, e.g.[22]) provides a convenient tool to handle stochastic convolutions directly in the Banach space. While we do not know about applications of this method to integral equations, it has been used successfully to treat parabolic stochastic differential equations, e.g. [13], [32]. We expect that such results can be extended to integral equations. Clearly, this approach works in more general Banach spaces, while the more classical technique is confined to the special structure of $L_{p}$.

In [12] we compared our linear results with those obtained in [13], [32]. In the context of the present paper it appears interesting to make a similar brief comparison concerning semilinear equations.

First note - as mentioned above - that the results of [32] are more general than those presented here in the sense that equations in Banach spaces of type 2 and even in UMD-spaces - are analyzed. Here we consider only $L_{p}$-spaces with $p \in[2, \infty)$. In addition, in [32], time-dependent operators $A(t)$ are considered. On the other hand, the aim of the present paper is to treat fractional differential equations and not only the differential equation case $\alpha=\beta=\gamma=1$, considered in [13], [32].

With $\alpha=\beta=\gamma=1$ our equation (1.1) reduces to the stochastic nonlinear differential equation

$$
\begin{equation*}
d u(t)=A u(t) d t+G(t, \omega, u(t)) d W_{t}+F(t, \omega, u(t)) d t \tag{8.1}
\end{equation*}
$$

It is this case, where we can compare our results to the results obtained by the abstract integration theory. Note that in abstract notation, $W_{t}$ is a cylindrical Wiener process in a separable Hilbert space $H$ and that, for fixed $u, G \in L_{p}([0, T] \times$ $\left.\Omega ; \gamma\left(H, L_{p}(B)\right)\right)$ where $\gamma\left(H, L_{p}(B)\right)$ denotes the space of $\gamma$-radonifying operators $H \rightarrow L_{p}(B)$. This is equivalent to writing the stochastic forcing in Krylov's notation

$$
G=\sum_{k=1}^{\infty} G^{k} w_{s}^{k}
$$

with (for fixed $u$ ) $\left\{G^{k}\right\}_{k=1}^{\infty} \in L_{p}\left([0, T] \times \Omega ; L_{p}\left(B, l_{2}\right)\right.$ ) (use, e.g., [32, Proposition 3.2.3]).

In [32], Theorem 8.3.3 gives existence and uniqueness of solutions for (8.1) in the space $L^{p}\left(\Omega ; C\left([0, T] ;(X, \mathcal{D} A)_{a, 1}\right)\right)$. However, the crucial Lemma 8.3.1 in [32], which establishes the contraction, allows also (as a special case $r=p$ ) to consider the space $L_{p}\left([0, T] \times \Omega ;(X, \mathcal{D} A)_{a, 1}\right)$. This compares best with our results. Note that the conditions (3.6), etc., are strict inequalities, so it makes no difference whether the results are stated in terms of $\left(L_{p}(B), \mathcal{D} A\right)_{a, 1}$ or of $\mathcal{D}(-A)^{a}$. With the assumption that $A$ is sectorial and independent of $t$, the Lipschitz conditions in [32] can be rewritten in our notation:
(F) For some $\theta_{F} \geq 0, a \in[0,1), a+\theta_{F}<1$,

$$
\left\|(-A)^{-\theta_{F}}(F(t, \omega, x)-F(t, \omega, y))\right\|_{L_{p}(B)} \leq L_{F}\|x-y\|_{\left(L_{p}(B), \mathcal{D} A\right)_{a, 1}}
$$

for all $t \in[0, T], \omega \in \Omega ; x, y \in\left(L_{p}(B), \mathcal{D} A\right)_{a, 1}$.
(G) For some $\theta_{B} \geq 0, a \in[0,1), a+\theta_{B}<\frac{1}{2}$,

$$
\|(-A)^{-\theta_{B}}\left(G(t, \omega, x)-G(t, \omega, y)\left\|_{L_{p}\left(B ; l_{2}\right)} \leq L_{G}\right\| x-y \|_{\left(L_{p}(B) ; \mathcal{D} A\right)_{a, 1}}\right.
$$

again for all $t \in[0, T]$ and $\omega \in \Omega, x, y \in\left(L_{p}(B), \mathcal{D} A\right)_{a, 1}$.
In our paper, the range of $G$ is specified to be $L_{p}\left(B ; l_{2}\right)$, so that we are restricted to $\theta_{B}=0$. (However, it would be easy to multiply the whole equation by $A^{\theta_{B}}$ to handle different values of $\theta_{B}$. In this case, our conditions on $\epsilon, \theta$ and $\delta_{0}$ would need to be replaced by analogous conditions on $\epsilon+\theta_{B}, \theta+\theta_{B}, \delta_{0}+\theta_{B}$.) The domain of $F$ and $G$ in our paper is $\mathcal{D}(-A)^{\theta}$, so our $\theta$ plays the role of $a$ in (G) above, while our $\epsilon$ corresponds to $-\theta_{F}$ in (F) above. So the condition $\theta_{F}+a<1$ translates exactly to our condition $-\epsilon+\theta<1$ which is (3.5) for $\alpha=\gamma=1$. Veraar's condition $a+\theta_{B}<\frac{1}{2}$ translates to $\theta+0<\frac{1}{2}$, which is (3.6) for $\alpha=\beta=1$.

While [32] requires $u_{0} \in L_{p}\left(\Omega ;\left(L_{p}(B, \mathbb{R}) ; \mathcal{D} A\right)_{a, 1}\right)$ (i.e. $\delta_{0}=\theta$ in our notation), our condition (3.7) requires slightly less, namely $\delta_{0}>\theta-\frac{1}{p}$. Essentially, Krylov's method yields the same regularity as the abstract integration theory, but, as mentioned above, it is restricted to $L_{p}$-spaces instead of general UMD-spaces.

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