

Basics: vectors, matrices, arrays

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Basic data structure: Matrix (array), elements: complex numbers. Let's limit ourselves at first to two-dimensional arrays.

```
>> rowvect=[1 2 3 4] % List of elements
>> 1:4 % Same with colon(:)-operator
ans = 1 2 3 4
% ans: previous non-assigned result
>> colvect=[1;2;3;4]
>> rowvect'== colvect % Transpose of row-vector
% NOTE lhs == rhs -> true/false
>> length(rowvect) % Nr. of elements
ans = 4
```

Vectors, matrices, arrays (continued)

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```
>> A=[1 2 3 4 ;5 6 7 8; 9 10 11 12]
>> [m,n]=size(A)    % --> m=3, n=4
>> [size(A,1) size(A,2)]
ans =
    3      4
>> v=-[1 2 3 4 ]
>> length(v)
ans =
    4
>> who, whos      % show workspace variables
```

- Column vector: $(m, 1)$ -matrix
- Row vector: $(1, n)$ -matrix
- Scalar: $(1, 1)$ -matrix
- Empty: $(m, 0)$ or $(0, n)$ -matrix

Creating arrays from smaller parts

Basics:
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- Square brackets [. . .] to define arrays
- Spaces (and/or commas) to separate columns (elements of row vector).
- Semi-colons (;) to separate rows (elements of column vector)
- `>> [3 4 5 ; 6 7 8]` is a 2-by-3 matrix
- If A and B are arrays with the same number of rows, then
`>> C = [A B]` is the array formed by stacking A and B side by side

```
>> A=ones(2,2);B=2*ones(2,3);[A B]
ans =
    1      1      2      2      2
    1      1      2      2      2
```

Creating arrays..., continued

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- If A and B are arrays with the same number of columns, then `>> [A ; B]` is the array formed by stacking A on top of B.
- So, `[[3 ; 6] [4 5 ; 7 8]]` is equal to
`[3 4 5; 6 7 8]`

Calculus with vectors

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- The numbers $0, 0.1, 0.2, \dots, 10$ can be assigned to the variable u by typing $u = 0:0.1:10;$
- $\text{length}(u)$ reveals us that there are 101 elements in u .
- To compute $w = 5 \sin u$ for $u = 0, 0.1, 0.2, \dots, 10$, the session is;

```
>>u = 0:0.1:10; % By 'misuse' of Matlab:  
>>w = 5*sin(u);>>for k=1:length(u)  
    %'Implied for-loop', w(k)=5*sin(u(k));  
    % vectorization end;
```

- This was our first acquaintance with “vectorization”.

“Scalar functions” support vectorization

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The previous example leads us to the following general idea: Functions which applied to a scalar produce a scalar result are called *scalar functions*. When such functions are applied to an array, they operate on every element of the array. Mathematical functions `help` `elfun`, `specfun` among others are of this type.

```
>> t = [-1 0 1];
>> y = exp(t)
y =
    0.3679    1.0000    2.7183
>> [exp(-1) exp(0) exp(1)]
ans =
    0.3679    1.0000    2.7183
```

“Scalar functions” support vectorization (contnd.)

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Assume we want to compute values of

$$y = e^{-x} \sin x$$

at a vector x . We need the vector

$$y = (e^{-x(1)} \sin(x(1)), e^{-x(2)} \sin(x(2)), \dots, e^{-x(n)} \sin(x(n)))$$

Here we need the pointwise product ($.*$) of two vectors:

```
>> x=-pi:.1:pi;  
>> y=exp(-x).*sin(x);
```

This is just the data we need for plotting. `>> plot(x, y)`

“Vector functions” (also support vectorization)

- Let **vector function** f mean that $f(\text{vector}) = \text{scalar}$. Such function operate on a matrix **columnwise** returnig a vector whose length is the length of rows (= nr. of columns). Examples are many that are classified under *datafunction*, `help datafun`.
- Example: `max`, `min`, `mean`, `sum`, ... Also many functions of type $f(\text{vector}) = \text{vector}$ behave similarly, except they applied to a matrix return a matrix “columnwise”. Examples: `sort`, `cumsum`, `cumprod`, ...
- These functions can be called to operate rowwise: for example `min(A, 2)` forms a column vector of row-minimums. Similarly for higher-dimensional arrays as well.

Functions for building vectors

colon(:,),linspace,logspace

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- `v=a:b, w=a:h:b;` default: $h=1$
- `v=linspace(a,b,N);` default: $N=100$
- `v=logspace(a,b,N);` $10^a, \dots, 10^b$, N points

```
>> 0:10; 0:.1:1;
>> 10:-2:0
ans =
    10      8      6      4      2      0
>> logspace(0,1,4)
ans =
    1.0000    2.1544    4.6416   10.0000
>> 10.^linspace(0,1,4)
ans =
    1.0000    2.1544    4.6416   10.0000
```

Note: Remember **semicolon (;**) for large N or small h .

Some functions for building matrices

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`eye, vander, hilb, zeros, ones, diag, rand, reshape, magic`
Complete list: `help elmat`

```
>> A = zeros(2,5)
>> B = ones(3)      % or ones(3,3)
>> R = rand(3,2)
>> N = randn(3,2)
>> D = diag(-2:2)
```

Compare `rand` and `randn` Try repeatedly

`>> R = rand(3,2)` Use (↑) in command window

Repeat : `>>rand('twister',0); R = rand(3,2)`

reshape

- Forms a matrix of given size for given data.
- Data will be placed in “frame” of given size in **column order**. (Matlab is column oriented.)
- Nr. of datapoints (`numel(data)`) has to match product of dimensions.

```
>> A=reshape(1:6,2,3) % 2x3 matrix from data ...
    1:6 in column order
>> B=reshape(1:6,3,2)' % Row-order
>> C=reshape(A,1,6)    % Back to vector 1:6
```

Matrices, building blocks

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```
>> A=reshape(1:6,2,3); B=ones(2,2),C=diag(1:3)
>> [A B]  % Side by side.
%ans =
    1      3      5      1      1
    2      4      6      1      1
>> [A;C]  On top of each other.
ans =
    1      3      5
    2      4      6
    1      0      0
    0      2      0
    0      0      3
>> cumsum(ones(3,4)) % What happens here?
% One of many ways to duplicate a column.
```

Matrix- and array algebra

A, B matrices, matching size, c scalar.

Matrix algebra

- A + B, A+c
- A*B matrix product
- A' (conjugate) transpose
- A.' transpose without conjugation
- A^p (A*A*...*A) Matrix power (A square matrix.)
- A\b
 $Ax = b \iff x = A\b$ (if A is invertible)

Array algebra “scalar extension”

- A + B, A+c
- A.*B Pointwise product
- A.^p, A.^B Pointwise power, p scalar, A and B of same size.
- A./B, c./A Pointwise divide. Subtle 1.0/A, 1.0./A, 1./A
- **Note:** c/A usually leads to an error.