# Matlab Basics Lecture 3

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- The command >>save saves all workspace variables into the file matlab.mat in the current directory.
- >>save A B saves just A and B.
- >>save myfile A B C\* saves A, B and all variables starting with C into myfile.mat. Note: If you happen to have a variable called myfile in your workspace, then this variable together with the above variables will be stored in matlab.mat (:-)).

# Files: Loading from a .mat-file

- >>load reads the file matlab.mat (in current directory or on matlab path) and loads all variables in the workspace, i.e. restores the state of the workspace after the corresponding save-command.
- >>load myfile does the same with myfile.mat.
- >>load myfile A B loads just variables A, B.

**Note:** These .mat-files are in Matlab's internal format. The next slide treats ASCII-file handling.

**Important:** save and load can't be used to save your session. Usually, much more important than saving variables, is saving the commands that created those variables, i.e. saving your session. For that you need scripts and .m - files.

#### ASCII Files, load textmat.dat

- To create user-readable files, append the flag -ascii to the end of a save command.
- Note: In this case, MATLAB does not append any extension to the file name, so you may want to add an extension such as .txt or .dat .

**Example:** Create a text-file textmat.dat outside Matlab.

textmat.dat:

1	2	3	4	
5	6	7	8	

```
>> load -ascii textmat.dat
>> % You can omit -ascii here
>> textmat
textmat =
    1    2    3    4
    5    6    7    8
```

Save a Matlab-variable into an ascii-file:

```
>> A=magic(3);
>> save -ascii Afile.dat A
>> % or: >> save -ascii -double Afile.dat A
>> clear
>> load Afile.dat
>> who
Your variables are: Afile
>> Afile
Afile =
    8 1 6
    3 5 7
          9
           2.
    4
```

See help save for more options.

MATLAB has several specialty functions to import different types of data.

Examples:

- xlsread for reading Excel files
- csvread for reading CSV delimeted data
- imread for reading image data
- audioread for reading audio data

There are countless others. When trying to import data, a good first step is to drag and drop the data file on the desktop, which will lead MATLAB trying to identify the file type.

Almost every "read" function in MATLAB has a corresponding "write" function

Examples:

- xlswrite for writing Excel files
- csvwrite for writing CSV delimeted data
- imwrite for writing image data
- audiowrite for writing audio data

- Read the file gasprices.csv in the MATLAB (available on the course web page)
- Find all entries in the file that have NaN entries, meaning they have no data, and replace the NaN value with value 1.37 (Hint: use isnan and logical indexing).
- Plot the data, using column year as the x-axis.

Interpolation Parameter fitting Noisy Data Problem: suppose we have some discrete measurement data, and we wish to construct new evaluation points within the range of those measurements.

This problem is called *interpolation*. Interpolation is a complicated problem that generally has no unique solution – in order for intepolation to provide a meaningful results, usually some *a priori* knowledge is needed.

Your primary interpolation tools within the MATLAB are the interp-functions. They are numbered 1–3, with the number telling the dimensionality of the data.

For our examples we'll use 1D data, so interp1.

Let us create a sample data by sampling values of a sine function randomly:

```
xpts = 12*rand(26,1)+6;
xpts = sort(xpts);
ypts = sin(xpts);
plot(xpts,ypts,'ro')
axis equal
```









Load the mat file interpData.mat into MATLAB, and perform interpolation of your choosing on the data. Can you guess the underlying function?

If you have n data points, you can (technically) fit a n-1 degree polynomial to the data.

If you try this on the previous data however

```
p = polyfit(xpts,ypts,45);
x = linspace(xpts(1),xpts(end),128);
plot(x,polyval(p,x));
```

you'll see why this is usually not a good idea.

Polynomial fit will pass through all the data points, but the oscillations of the high-degree polynomial will make the result unusable.

However, if you can select the points on which you fit, the results can change dramatically:

```
x = linspace(-5,5,13); % datapoints
xx = linspace(-5,5,256); % interpolation points
f = @(x)1./(1+x.^2); % the function fitted for
pp = polyfit(x,f(x))
% Plot
plot(xx,f(xx),xx,polyval(pp,xx))
```

```
x = 5*cos(pi*(0:12)./12);
xx = linspace(-5,5,256); % interpolation points
f = @(x)1./(1+x.^2); % the function fitted for
pp = polyfit(x,f(x))
% Plot
plot(xx,f(xx),xx,polyval(pp,xx))
```

Unlike in interpolation, curve fitting can be thought of as a *minimization*-problem.

You'll want to find a curve that is as close to data as possible within the parameters, but does not necessarily need to pass through every datapoint.

# **Curve fitting - Example**

The very basic example — fitting a trend line on a dataset.

```
% create some data
x = 5:21;
y = 3.5 \times x + 4 + 4 \times randn(size(x)) + 5;
plot(x,y,'ro')
%% the hardcore mathy way
V = [x', ones(size(x'))];
coeff = V \setminus v';
xfit = linspace(x(1), x(end), 256);
yfit = coeff(1) * xfit + coeff(2);
plot(x,y,'ro',xfit,yfit)
%% The more consistent way
p = polyfit(x, y, 1);
plot(x,y,'ro',xfit,polyval(p,xfit))
```

Let's try to fit a polynomial to US census data.

```
% create time vectors -- dense and sparse
t = 1900:10:1990;
tt = 1900:1:2010;
pop = [76 92 106 122 132 150 179 203 226 248];
% for show, try the maximum degree polynomial
P = polyfit(t,pop,length(pop)-1);
plot(tt,polyval(P,tt));
% It fails -- as is expected
P = polyfit(t,pop,3);
plot(tt,polyval(P,tt));
```

## Nonlinear fitting

```
x = 20:65;
y = [0 0 0 1 2 5 15 65 71 79 55 48 46 26 25 25 16 9 ...
   18 ...
    8 8 6 4 6 5 5 2 6 4 2 0 0 1 1 1 0 1 1 0 0 0 0 0 ...
        2 0 0];
f = 0 (beta, x) beta (1) *x.^9 .* exp(-beta (2) *x);
fobj = Q(lam)norm(f(lam, x) - y);
beta0 = [1 - 1];
betaOpt = fminsearch(fobj,beta0);
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xfit = linspace(20,65,128);
plot(xfit, f(betaOpt, xfit), x, y)
```

#### Noise gating - example

```
% Create and visualize the data
t = linspace(0, 0.5*pi, 256);
carrier = sin(2*pi*t) + sin(6*2*pi*t);
plot(t,carrier)
%% add some noise
noisySignal = carrier + 2*rand(size(carrier))-1;
plot(t,carrier,t,noisySignal)
%% Go to frequency spectrum
X = fft(carrier);
plot(abs(X))
Xnoisy = fft(noisySignal);
plot(abs(Xnoisy))
%% Identify the noise component, and gate it out
Xnoisy(abs(Xnoisy) < 30) = 0;
%% Go back to time domain
xnew = real(ifft(Xnoisy));
plot(t,carrier,t,xnew)
```