

# Exercise 4, Image compression with svd

HA 3.12.2018

```
close all;format compact;clear
img=imread('Seurasaari.jpg');
[M,N]=size(img)
```

```
M = 2736
N = 10944
```

```
imshow(img)
```

## Convert to double

```
dimg=im2double(img); % dimg is 3-dim array.
size(dimg)
```

```
ans = 1x3
      2736      3648      3
```

```
imshow(dimg)
```

```
Warning: Image is too big to fit on screen; displaying at 25%
```

```
title('Original image');
```

Original image



## Take svd of all 3 layers.

Here semicolons are important, extremely!

```
tic
[u1,s1,v1]=svd(dimg(:,:,1)); % Layer 1, Red
[u2,s2,v2]=svd(dimg(:,:,2)); % Layer 2, Green
[u3,s3,v3]=svd(dimg(:,:,3)); % Layer 3, Blue
T=toc
```

```
T = 67.0671
```

```
%{
T =
    52.6644
%}
```

## Let's have a look at the singular values:

```
D1=diag(s1);D2=diag(s2);D3=diag(s3);
[D1(1:20) D2(1:20) D3(1:20)]
```

```
ans = 20x3
103 ×
    1.0052    1.1472    1.3175
    0.1336    0.1488    0.1986
    0.1112    0.0838    0.0847
    0.0835    0.0638    0.0798
    0.0596    0.0436    0.0509
    0.0516    0.0369    0.0408
    0.0440    0.0320    0.0378
    0.0385    0.0291    0.0327
    0.0374    0.0247    0.0298
    0.0343    0.0240    0.0286
    ⋮
```

```
[D1(1:20) D2(1:20) D3(1:20)]./[D1(1) D2(1) D3(1)] %This works in new versions
```

```
ans = 20x3
    1.0000    1.0000    1.0000
    0.1329    0.1297    0.1507
    0.1107    0.0731    0.0643
    0.0830    0.0556    0.0606
    0.0593    0.0380    0.0386
    0.0514    0.0321    0.0310
    0.0438    0.0279    0.0287
    0.0383    0.0253    0.0248
    0.0372    0.0216    0.0226
    0.0341    0.0209    0.0217
    ⋮
```

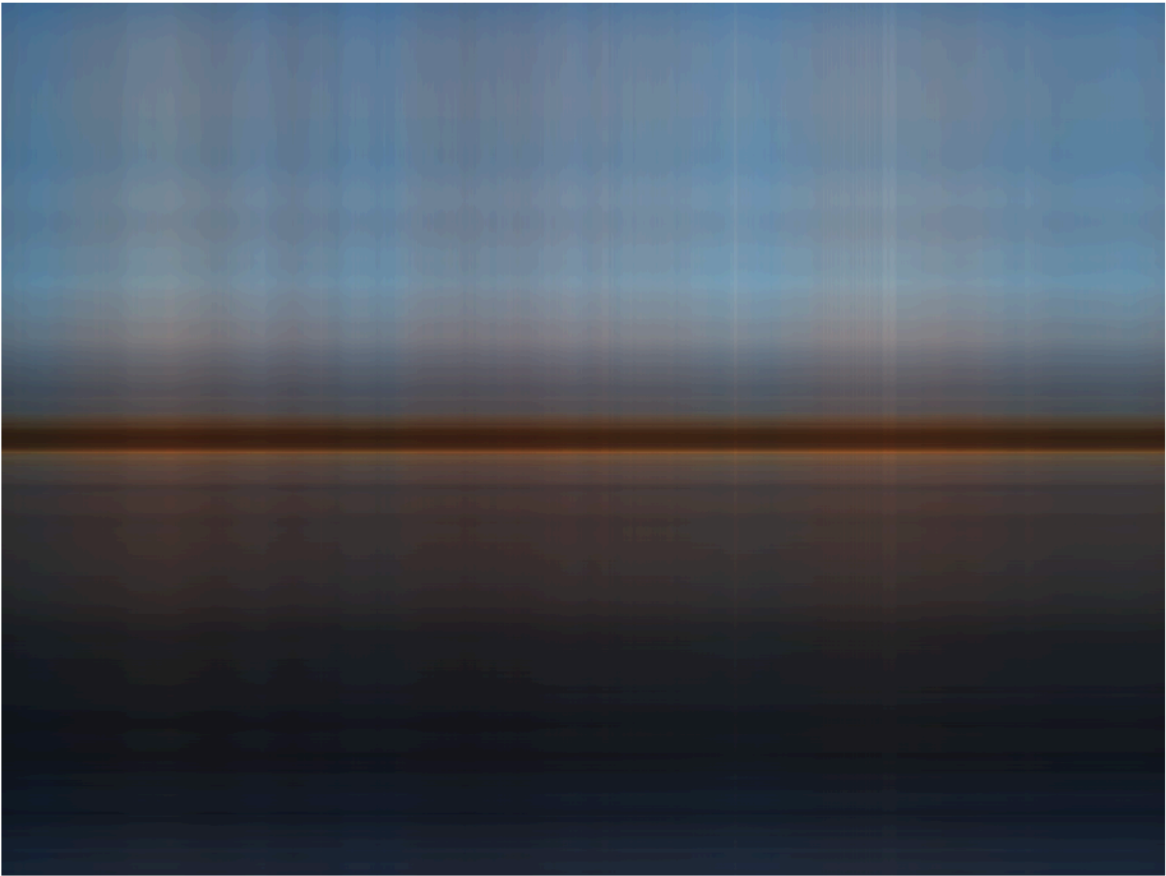
```
% The first few seem to dominate.
```

## Show images in separate windows

```
close all
for k=[1:5 10 100];
    M1=u1(:,1:k)*s1(1:k,1:k)*v1(:,1:k)';
    M2=u2(:,1:k)*s2(1:k,1:k)*v2(:,1:k)';
    M3=u3(:,1:k)*s3(1:k,1:k)*v3(:,1:k)';
    kfig=k;
    if k==10
        kfig=6;
    elseif k==100
        kfig=7;
    end
    figure(kfig)
    imshow(cat(3,M1,M2,M3))
    title(['First ',num2str(k),' singular values'])
end
```

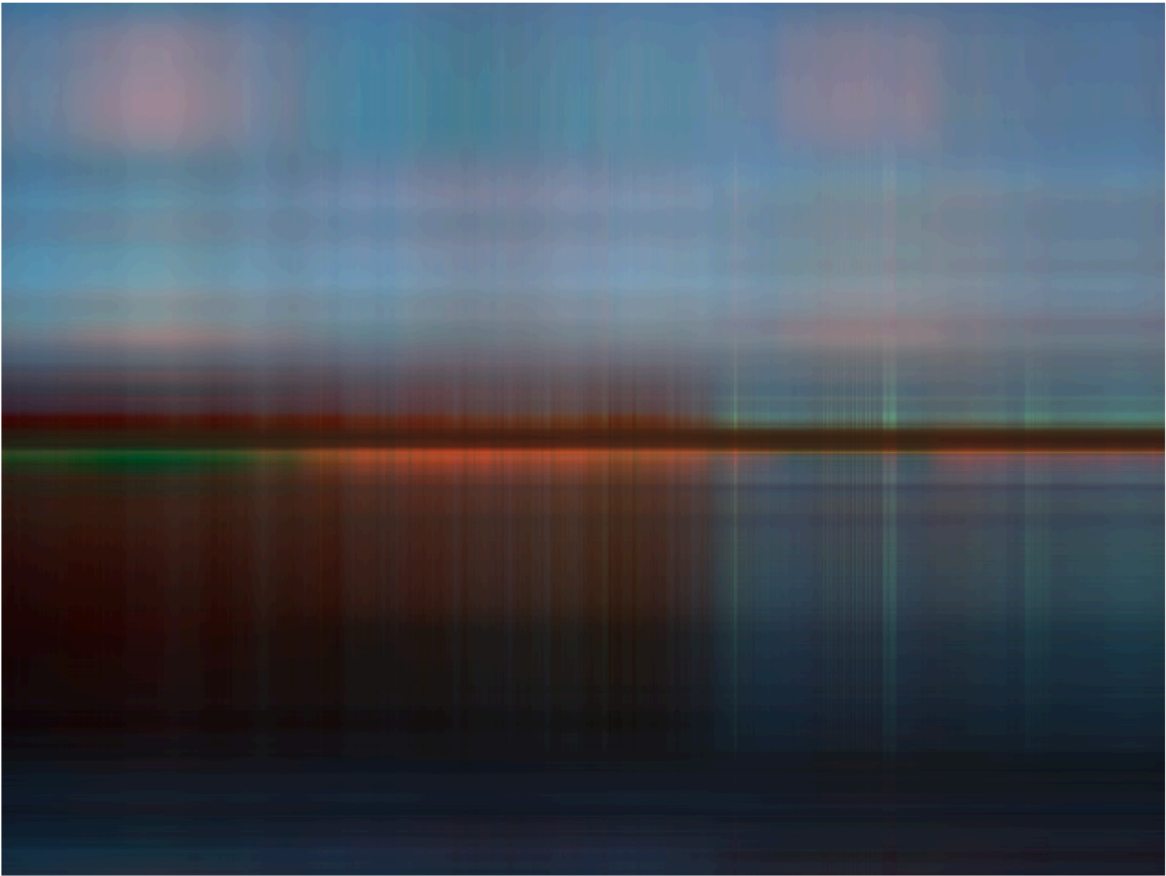
```
Warning: Image is too big to fit on screen; displaying at 25%
```

**First 1 singular values**



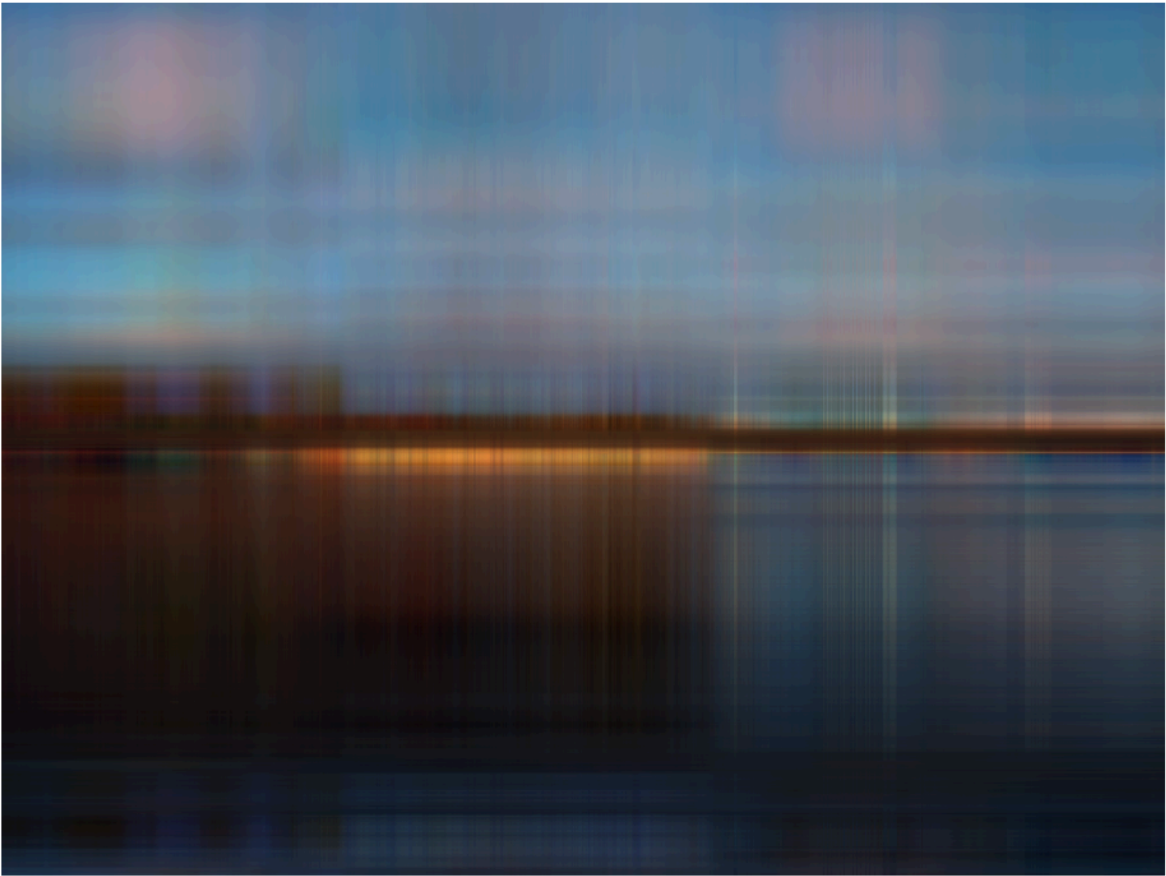
Warning: Image is too big to fit on screen; displaying at 25%

First 2 singular values



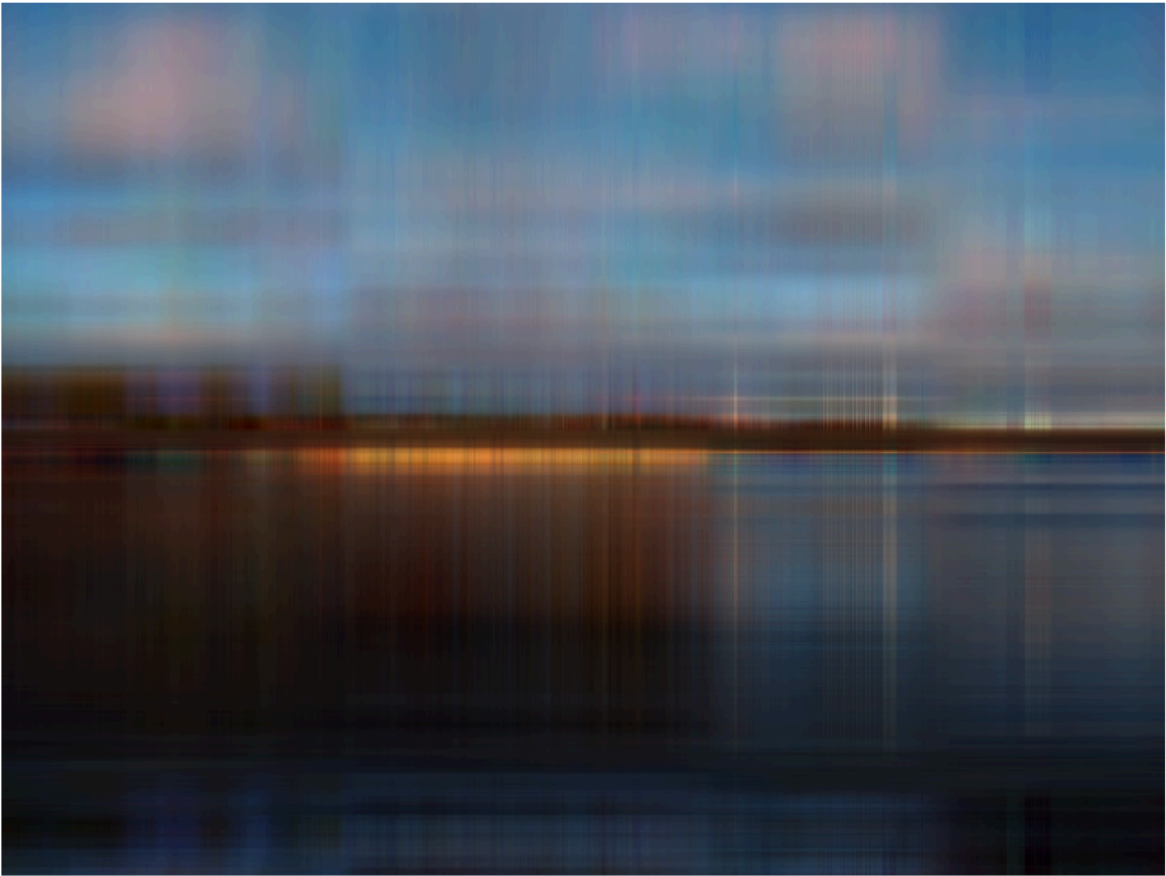
Warning: Image is too big to fit on screen; displaying at 25%

**First 3 singular values**



Warning: Image is too big to fit on screen; displaying at 25%

First 4 singular values



Warning: Image is too big to fit on screen; displaying at 25%

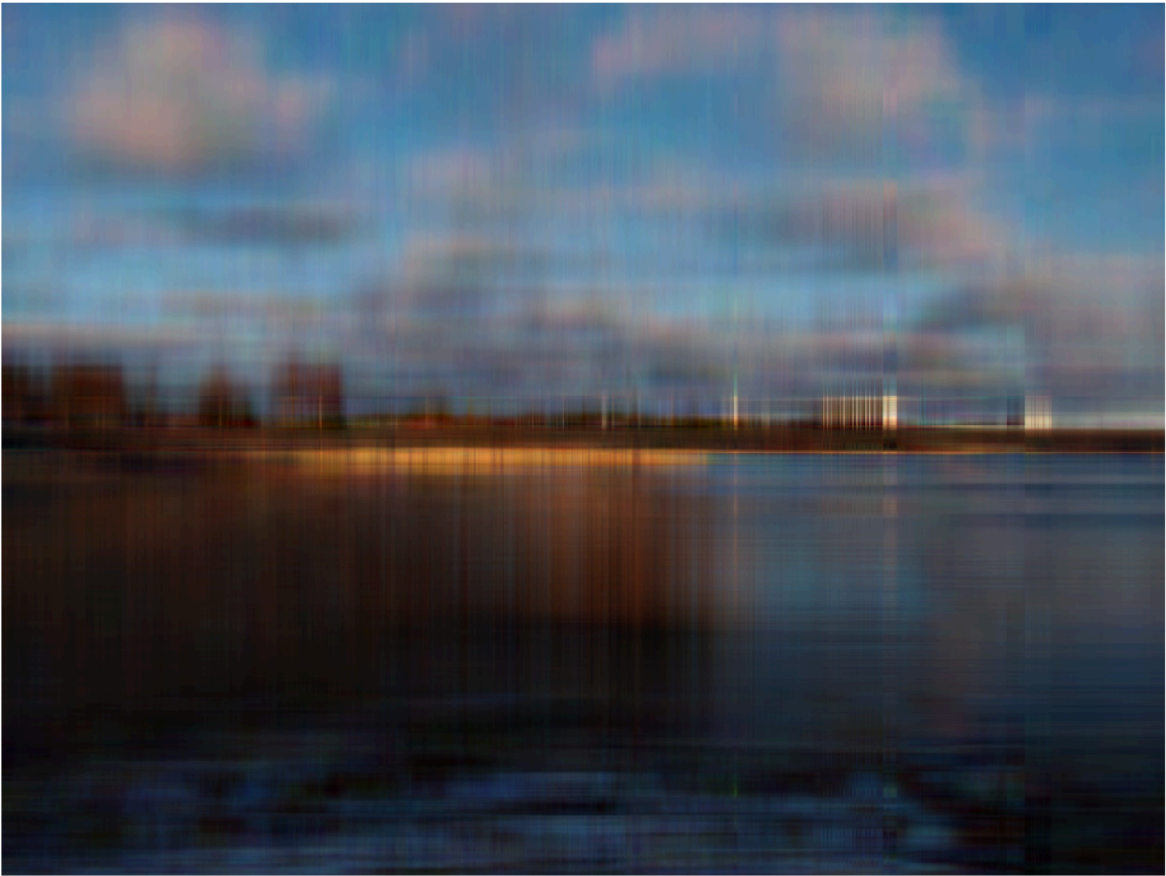
**First 5 singular values**



Warning: Image is too big to fit on screen; displaying at 25%



**First 10 singular values**



Warning: Image is too big to fit on screen; displaying at 25%

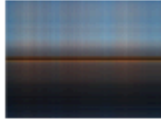
First 100 singular values



## Use "matrix of windows" with subplot

```
close all
for k=1:8
    M1=u1(:,1:k)*s1(1:k,1:k)*v1(:,1:k)';
    M2=u2(:,1:k)*s2(1:k,1:k)*v2(:,1:k)';
    M3=u3(:,1:k)*s3(1:k,1:k)*v3(:,1:k)';
    subplot(4,2,k)
    imshow(cat(3,M1,M2,M3))
    title(['First ',num2str(k),' singular values'])
end
```

**First 1 singular values**



**First 2 singular values**



**First 3 singular values**



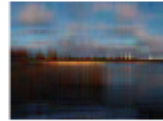
**First 4 singular values**



**First 5 singular values**



**First 6 singular values**



**First 7 singular values**



**First 8 singular values**



## Is this useful?

Example: If you send a camera to Jupiter, you can do the svd's there and only need to send back to earth the  $n$  most significant singular values along with the corresponding columns of  $U$  and  $V$ . The value of  $n$  is of course "picture-dependent".